

# Phase-field cohesive zone crack propagation model for hard-soft architected materials

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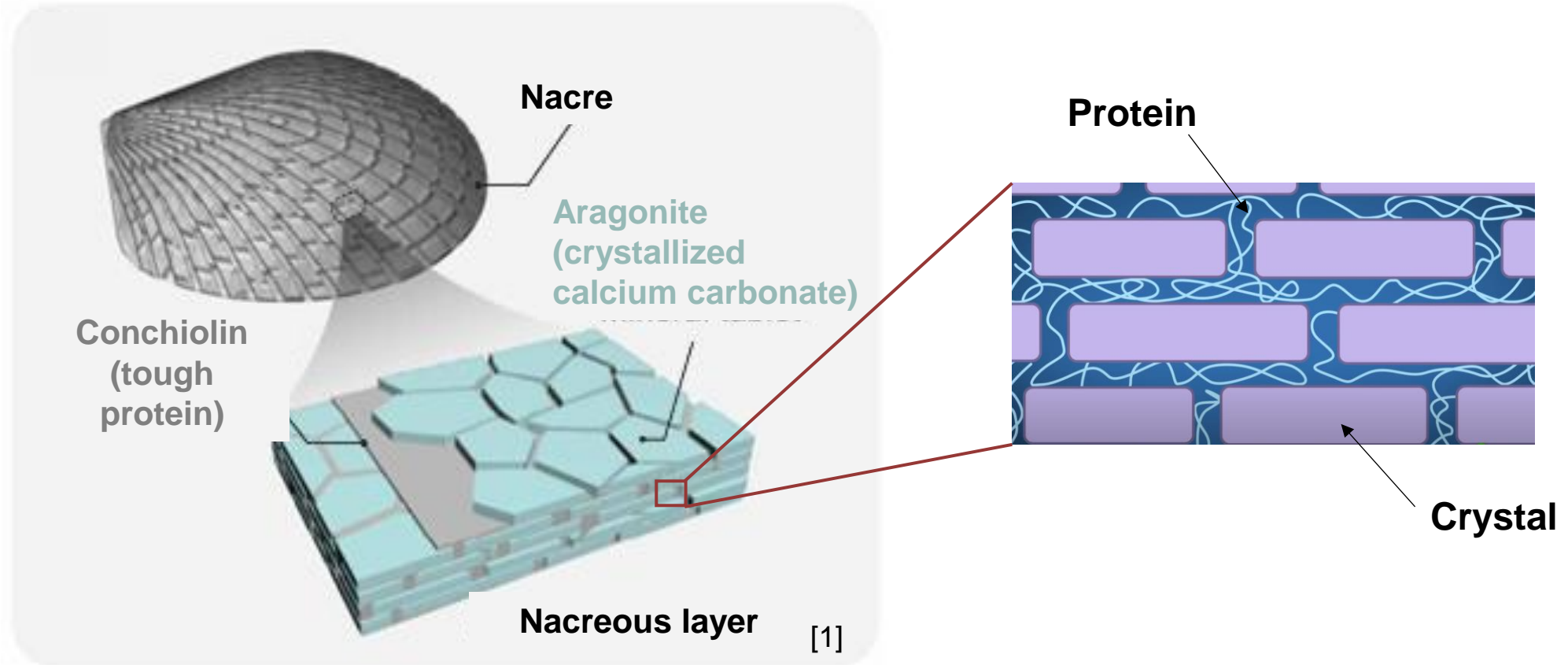
ARCHITECTED MATERIALS AND  
ADDITIVE MANUFACTURING LAB



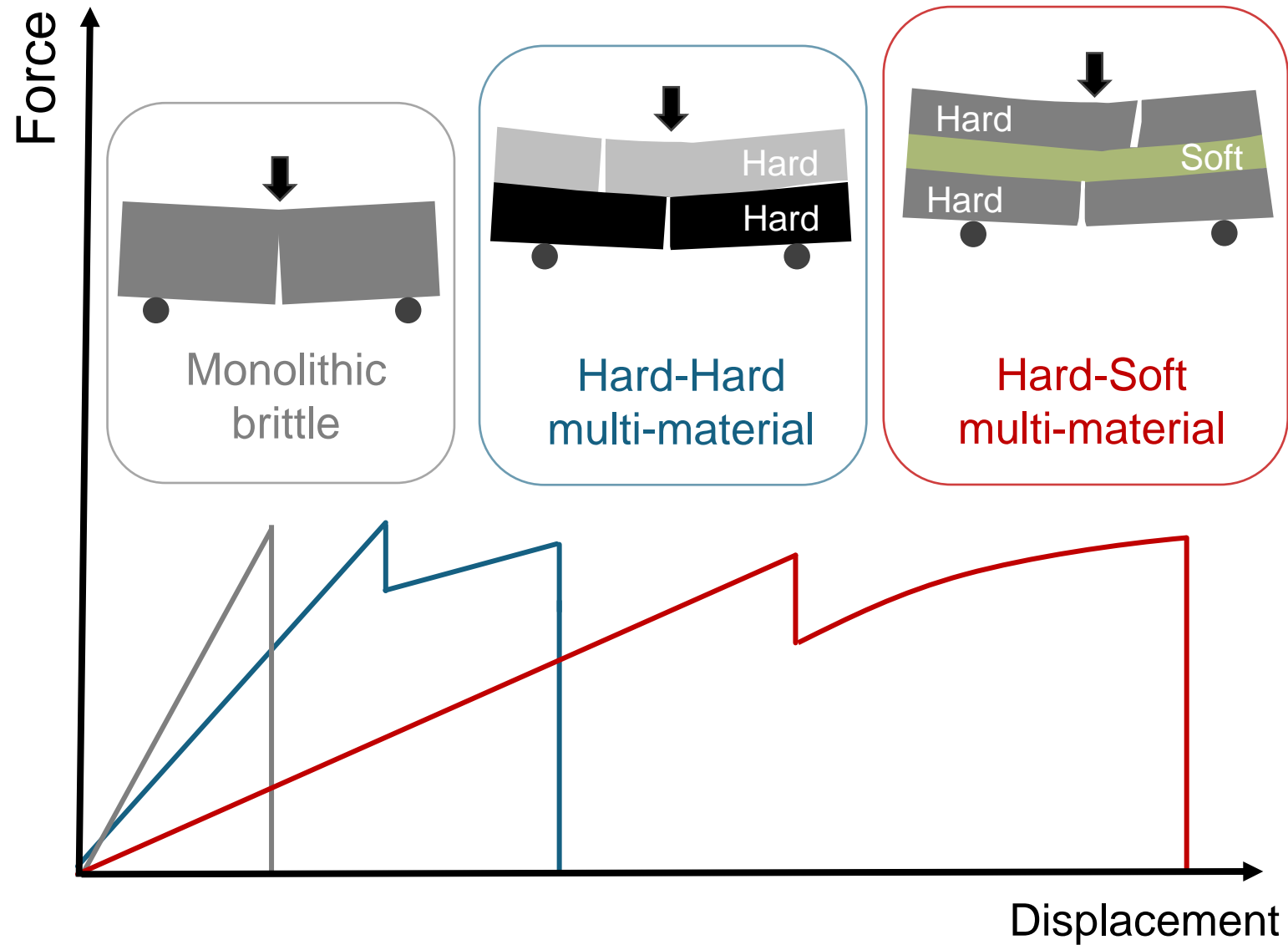
**PRINCETON**  
**ENGINEERING**



# Nacre's overlapping crystal-protein plates provides toughness



# Hypothesis: hard-soft multi-materials enhance mechanical performance

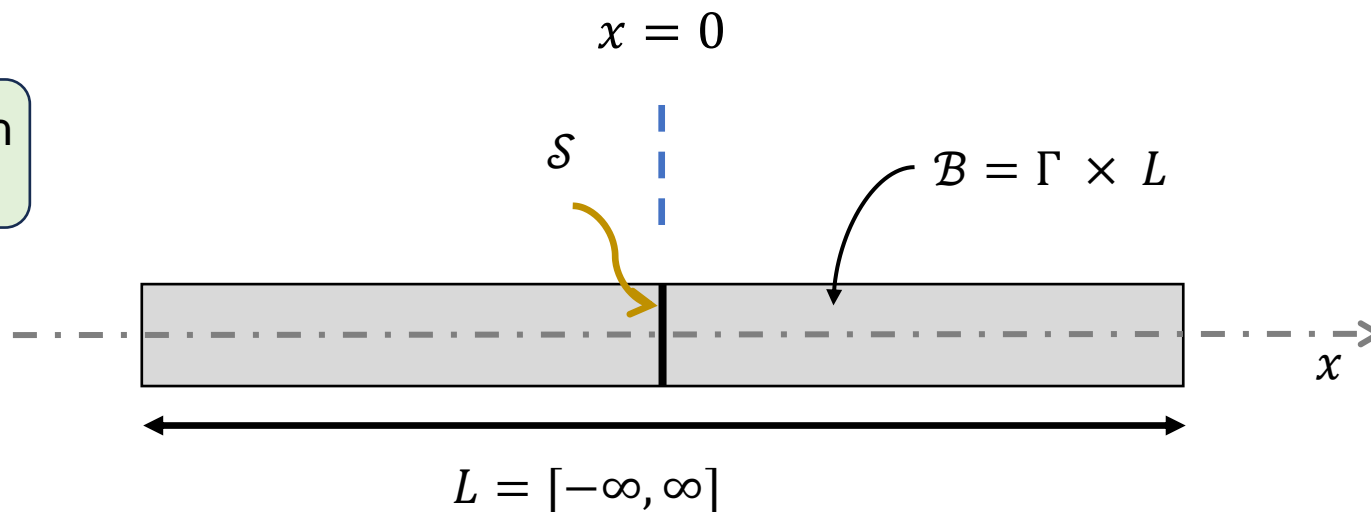


How do we numerically investigate fracture in **hard-soft multi-material assemblies** to better understand the toughening mechanisms involved in their response to fracture?

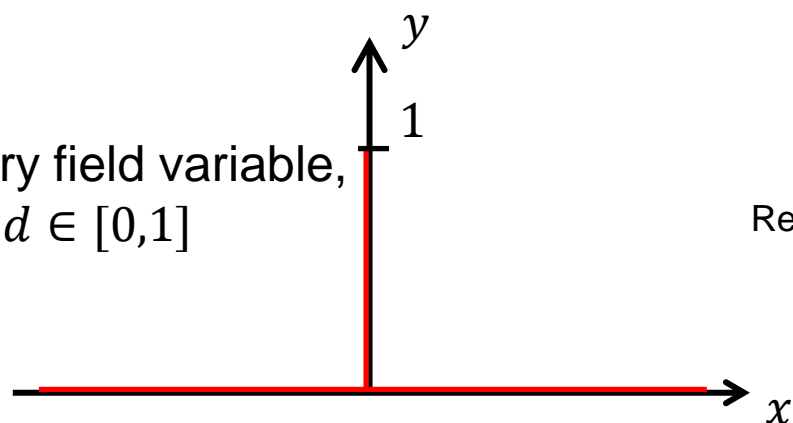


# How do we numerically investigate fracture in such composite materials?

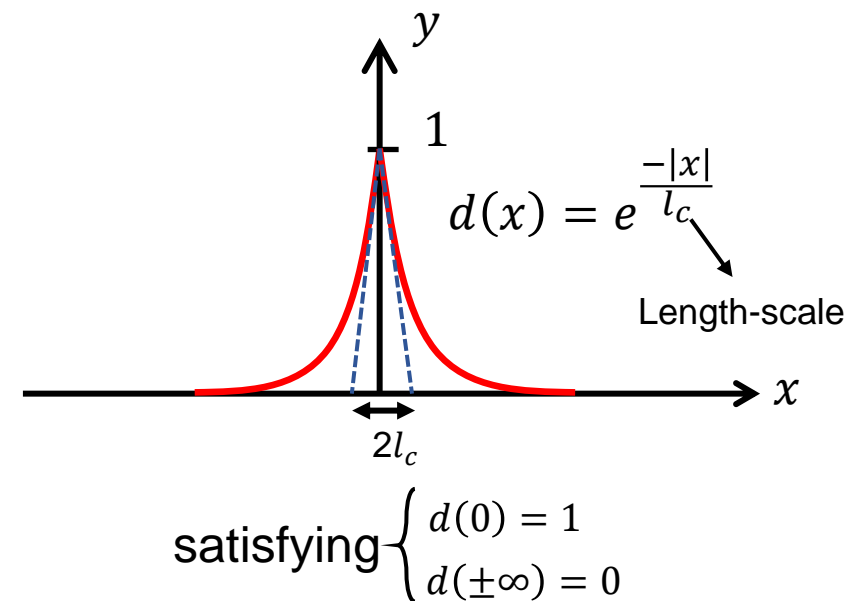
Phase-field approach for modeling fracture



$d \equiv$  auxiliary field variable,  
 $d \in [0,1]$

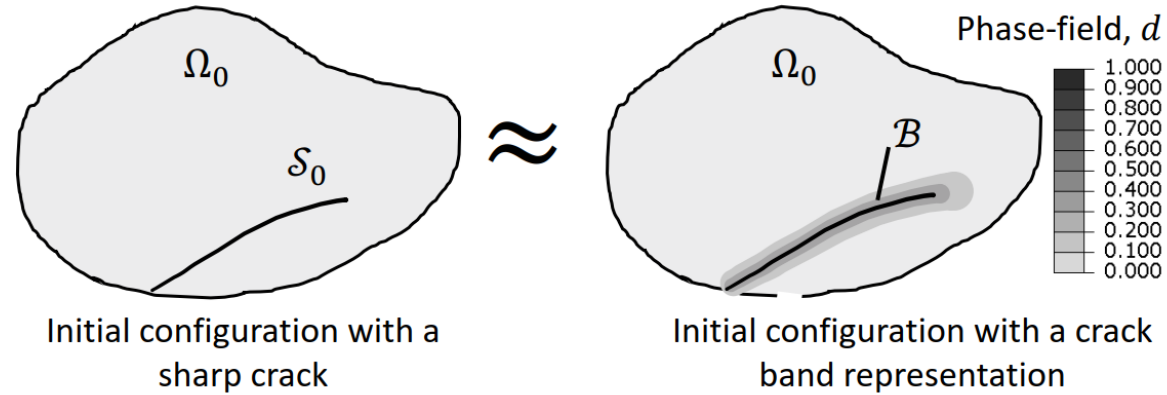


Regularizing non-smooth sharp crack with a diffuse crack topology



# Phase-field captures crack propagation through regularization of sharp crack topology

$\mathcal{S}_0$ : sharp crack topology  
 $\mathcal{B}$ : diffuse damage band



**Regularize the sharp crack topology by a limited diffuse damage band**

A time-dependent phase-field damage variable  $d(\mathbf{X}, t) \in [0,1]$  is introduced where  $d = 0$  indicates **no fracture** and  $d = 1$  indicates **complete fracture**

**Crack surface energy**

$$\Psi(\mathcal{S}_0) = \int_{\mathcal{S}_0} G_c \, dA \approx \int_{\Omega_0} G_c \gamma(d, \nabla d) \, dV$$

$G_c$ : Fracture energy     $\gamma$ : crack surface density function

where  $\gamma(d, \nabla d) = \frac{1}{c_\alpha} \left[ \frac{1}{l_c} \alpha(d) + l_c |\nabla d|^2 \right]$

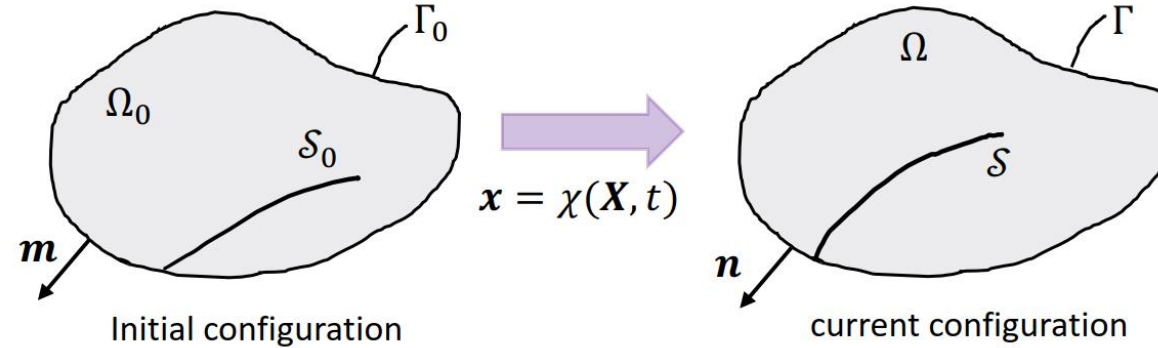
$l_c$ : length scale

$$c_\alpha = 4 \int_0^1 \sqrt{\alpha(\beta)} \, d\beta = \begin{cases} 2, & \alpha(d) = d^2 & \text{AT2} \\ \frac{8}{3}, & \alpha(d) = d & \text{AT1} \end{cases}$$



# Phase-field captures crack propagation through regularization of sharp crack topology

## Kinematics



$$\mathbf{F} = \nabla \chi(\mathbf{X}, t) = \mathbf{I} + \nabla \mathbf{u}$$

deformation gradient

$\mathbf{u}$ : displacement field

## Total potential energy of the system

$$\underbrace{\Pi(\mathbf{u}, d)}_{\text{total potential}} = \underbrace{\int_{\Omega_0} g(d) \psi_0(\mathbf{F}) dV}_{\text{strain energy}} + \underbrace{\int_{\Omega_0} G_c \gamma(d, \nabla d) dV}_{\text{crack surface energy}} - \underbrace{\left( \int_{\Omega_0} \mathbf{b}_0 \cdot \mathbf{u} dV + \int_{\Gamma_0} \mathbf{t}_0 \cdot \mathbf{u} dA \right)}_{\text{external energy}}$$

Strain energy density
Body forces
Applied traction

## Variational principle

$$g(d) = (1 - d)^2: \text{degradation function}$$

$$(\mathbf{u}(\mathbf{x}), d(\mathbf{x})) = \text{Arg}\{\min \Pi(\mathbf{u}, d)\} \quad \text{subject to } \dot{d}(\mathbf{x}) > 0, d(\mathbf{x}) \in [0, 1], \mathbf{x} \in \mathbb{R}^n, n = 1, 2, 3$$



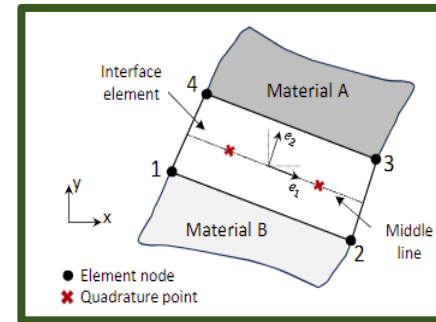
# Contribution of interface to the crack surface energy can be accounted for separately

## Updated crack surface energy

$$\int_{\Omega_0} G_c^b \gamma(d, \nabla d) dV + \int_{\Gamma_0} G^i dA$$

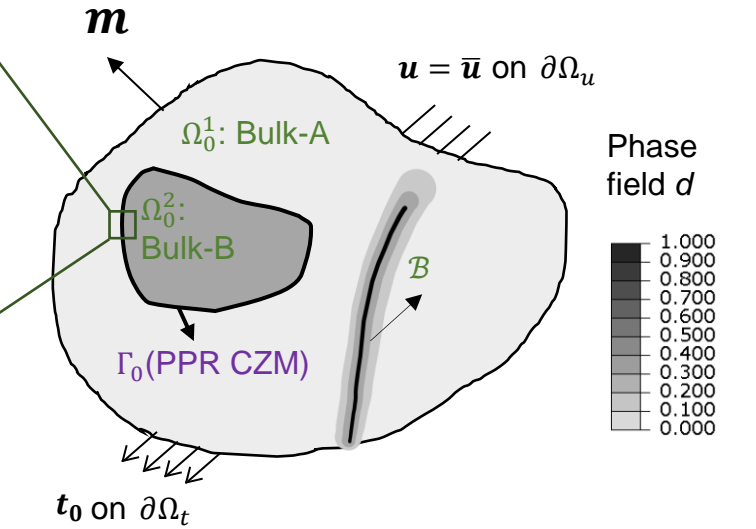
Bulk
Interface

$G_c^b$ : fracture energy of the bulk material  
 $G^i$ : fracture energy dissipated at the interface



$\Delta \mathbf{u} = \mathbf{u}_1 - \mathbf{u}_2$  displacement jump vector

$$\int_{\Gamma_0} G^i dA = \int_{\Gamma_0} (\Delta \mathbf{u})^T \mathbf{T} dA$$



$\mathcal{B}$ : smeared crack – modeled by Phase-field  
 $\Gamma_0$ : Interface – modeled by PPR CZM

## Updated total potential energy of the system

$$\underbrace{\Pi(\mathbf{u}, d)}_{\text{total potential}} = \underbrace{\int_{\Omega_0} g(d) \psi_0(\mathbf{F}) dV}_{\text{strain energy}} + \underbrace{\int_{\Omega_0} G_c^b \gamma(d, \nabla d) dV + \int_{\Gamma_0} (\Delta \mathbf{u})^T \mathbf{T} dA}_{\text{crack surface energy}} - \underbrace{\left( \int_{\Omega_0} \mathbf{b}_0 \cdot \mathbf{u} dV + \int_{\Gamma_0} \mathbf{t}_0 \cdot \mathbf{u} dA \right)}_{\text{external energy}}$$

Bulk
Interface



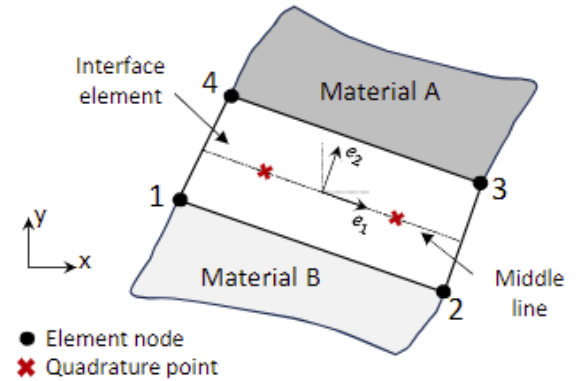


# Park-Paulino-Roesler (PPR) [1] was used to capture dissipated energy at interfacial zones

User-Element Subroutine (UEL) for Abaqus

$$\phi(\Delta \mathbf{u}_n, \Delta \mathbf{u}_t) = \min(G_c^{int_n}, G_c^{int_t}) + \left[ \Gamma_n \left( 1 - \frac{\Delta \mathbf{u}_n}{\delta_n} \right)^\alpha \left( \frac{m}{\alpha} + \frac{\Delta \mathbf{u}_n}{\delta_n} \right)^m + \langle G_c^{int_n} - G_c^{int_t} \rangle \right] \times \left[ \Gamma_t \left( 1 - \frac{|\Delta \mathbf{u}_t|}{\delta_t} \right)^\beta \left( \frac{n}{\beta} + \frac{|\Delta \mathbf{u}_t|}{\delta_t} \right)^n + \langle G_c^{int_t} - G_c^{int_n} \rangle \right]$$

$G_c^{int_n}, G_c^{int_t}$ : Energies for mode I and mode II fracture, respectively  
 $\Gamma_n, \Gamma_t$ : Energy constants  
 $\Delta \mathbf{u}_n, \Delta \mathbf{u}_t$ : Normal and tangential components of the displacement jump  
 $\delta_n, \delta_t$ : Final crack openings representing complete failure in the normal and tangential directions, respectively  
 $\alpha, \beta$ : shape parameters



• Normal traction force

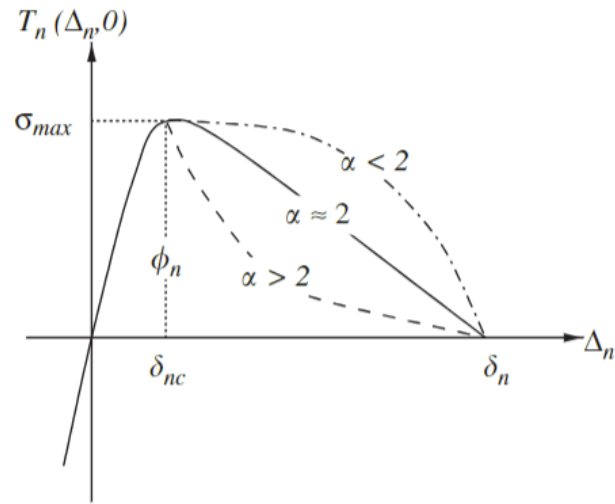
$$T_n(\Delta \mathbf{u}_n, \Delta \mathbf{u}_t) = \frac{\Gamma_n}{\delta_n} \left[ m \left( 1 - \frac{\Delta \mathbf{u}_n}{\delta_n} \right)^\alpha \left( \frac{m}{\alpha} + \frac{\Delta \mathbf{u}_n}{\delta_n} \right)^{m-1} - \alpha \left( 1 - \frac{\Delta \mathbf{u}_n}{\delta_n} \right)^{\alpha-1} \left( \frac{m}{\alpha} + \frac{\Delta \mathbf{u}_n}{\delta_n} \right)^m \right] \times \left[ \Gamma_t \left( 1 - \frac{|\Delta \mathbf{u}_t|}{\delta_t} \right)^\beta \left( \frac{n}{\beta} + \frac{|\Delta \mathbf{u}_t|}{\delta_t} \right)^n + \langle G_c^{int_t} - G_c^{int_n} \rangle \right]$$

$$T_n(\delta_{nc}, 0) = \sigma_{max}$$

• Tangential traction force

$$T_t(\Delta \mathbf{u}_n, \Delta \mathbf{u}_t) = \frac{\Gamma_t}{\delta_t} \left[ n \left( 1 - \frac{|\Delta \mathbf{u}_t|}{\delta_t} \right)^\beta \left( \frac{n}{\beta} + \frac{|\Delta \mathbf{u}_t|}{\delta_t} \right)^{n-1} - \beta \left( 1 - \frac{|\Delta \mathbf{u}_t|}{\delta_t} \right)^{\beta-1} \left( \frac{n}{\beta} + \frac{|\Delta \mathbf{u}_t|}{\delta_t} \right)^n \right] \times \left[ \Gamma_n \left( 1 - \frac{\Delta \mathbf{u}_n}{\delta_n} \right)^\alpha \left( \frac{m}{\alpha} + \frac{\Delta \mathbf{u}_n}{\delta_n} \right)^m + \langle G_c^{int_t} - G_c^{int_n} \rangle \right] \left( \frac{\Delta \mathbf{u}_t}{|\Delta \mathbf{u}_t|} \right)$$

$$T_t(0, \delta_{tc}) = \tau_{max}$$



## Updated crack surface energy

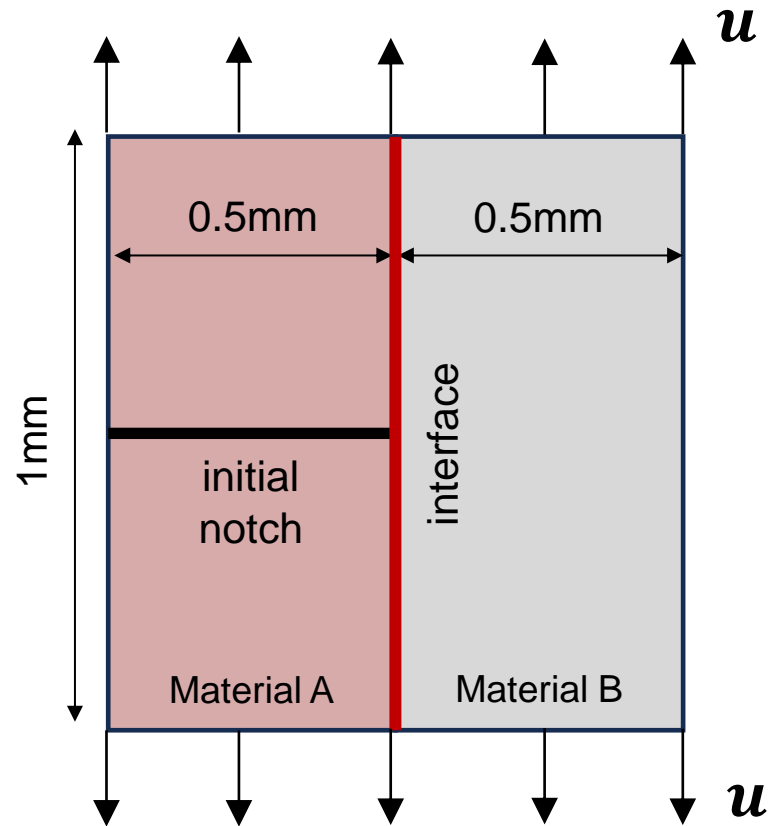
$$\int_{\Gamma_0} G^i dA = \int_{\Gamma_0} (\Delta \mathbf{u})^T \mathbf{T} dA \quad \text{where} \quad \Delta \mathbf{u} = \mathbf{u}_1 - \mathbf{u}_2 \quad \text{and} \quad \mathbf{T} = (T_n, T_t)$$

Displacement jump                      Traction force vector

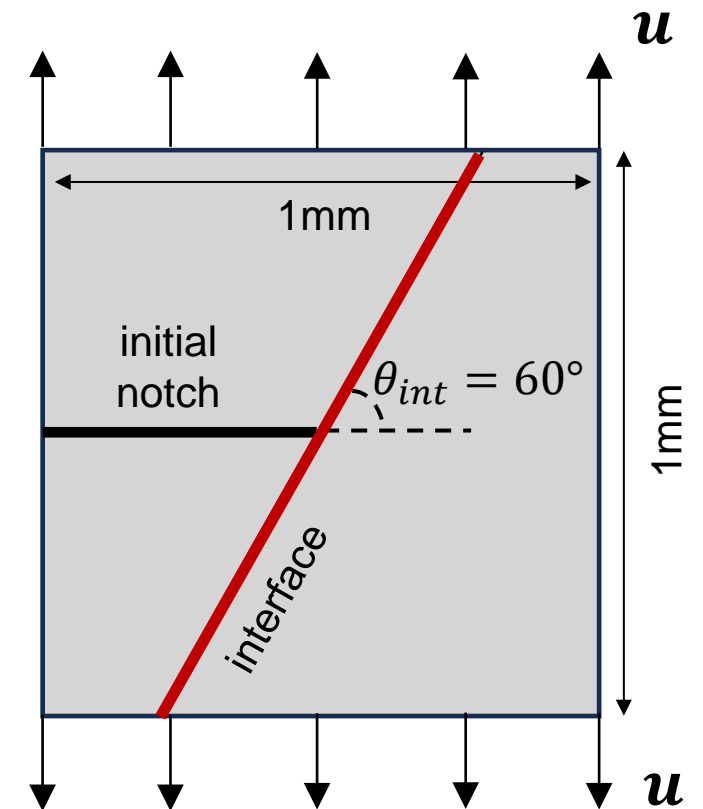


# Crack propagation was investigated for four cases of hard-hard and hard-soft composites

**Case I: hard-hard bi-layer composite with interface perpendicular to initial notch direction**

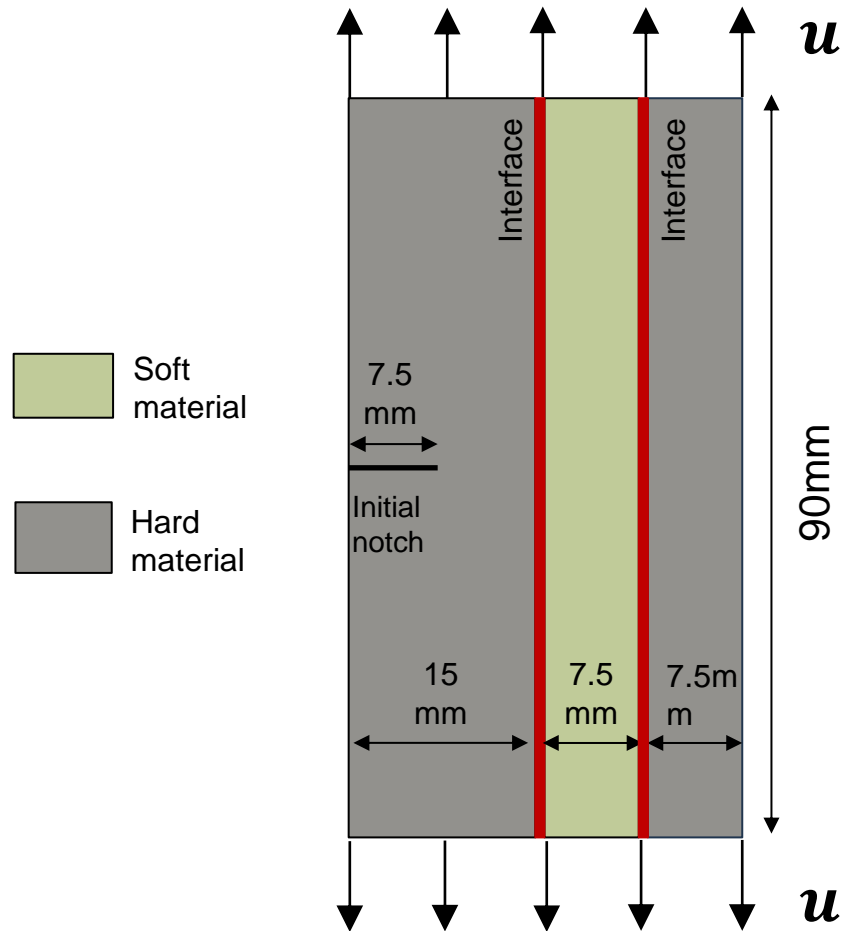


**Case II: solid with crack impinging on an incline interface**

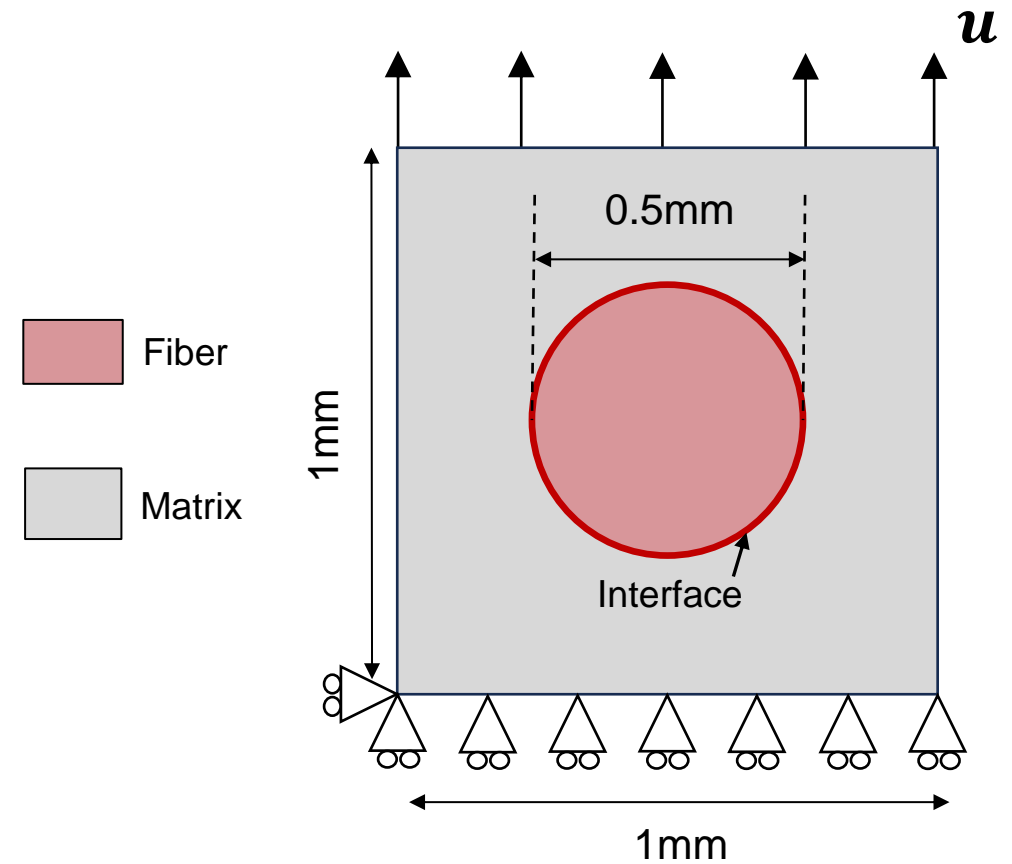


# Crack propagation was investigated for four cases of hard-hard and hard-soft composites

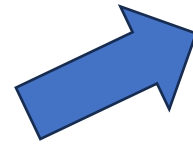
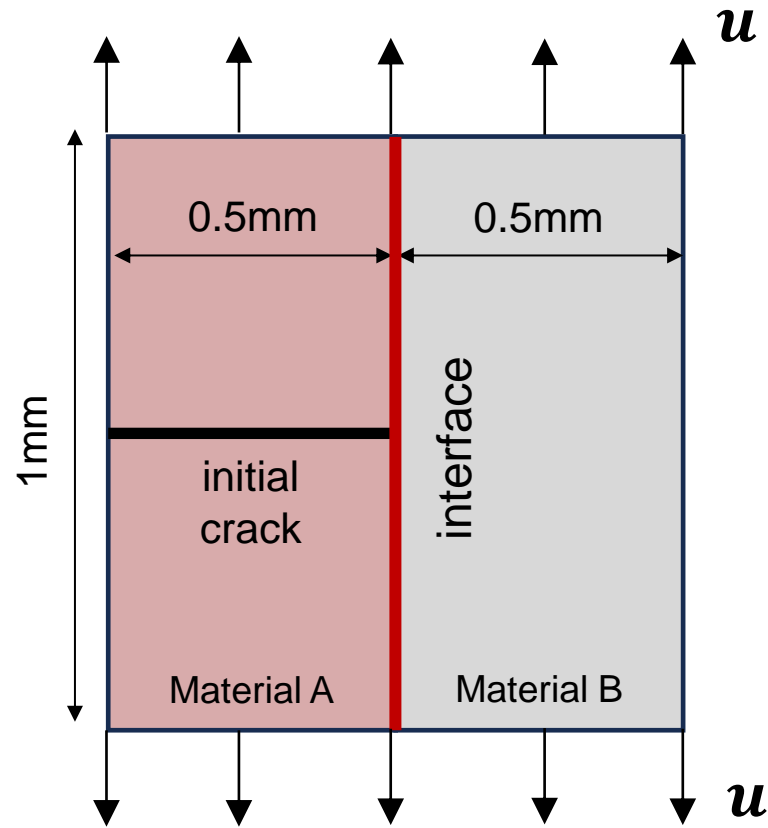
## Case III: hard-soft-hard tri-layer composite with interface perpendicular to initial notch direction



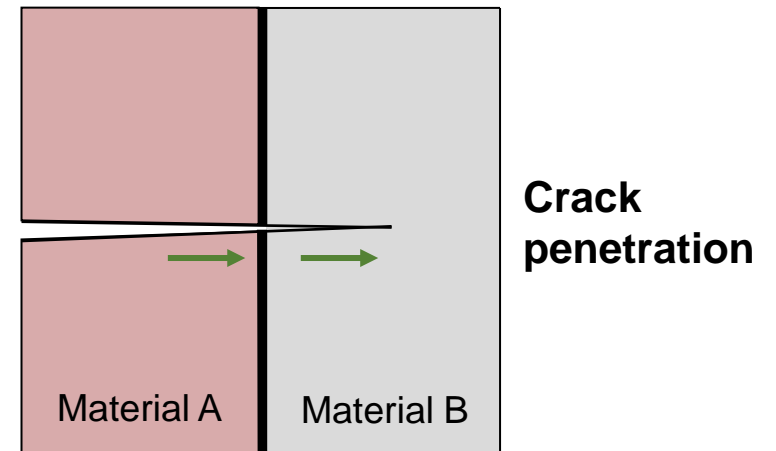
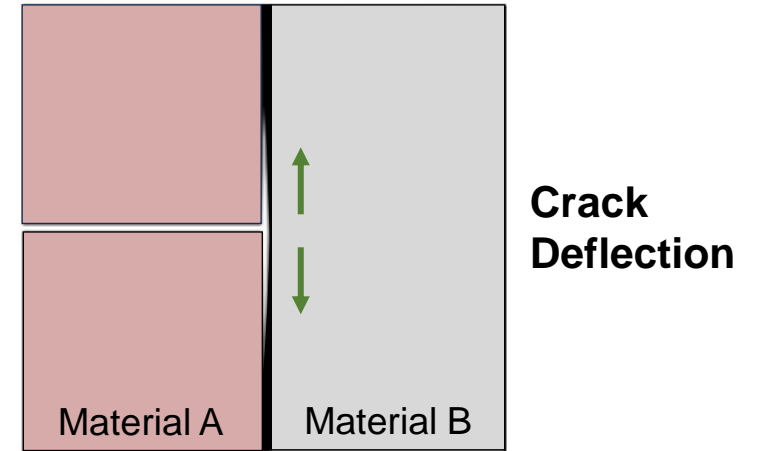
## Case IV: fiber-reinforced matrix composite



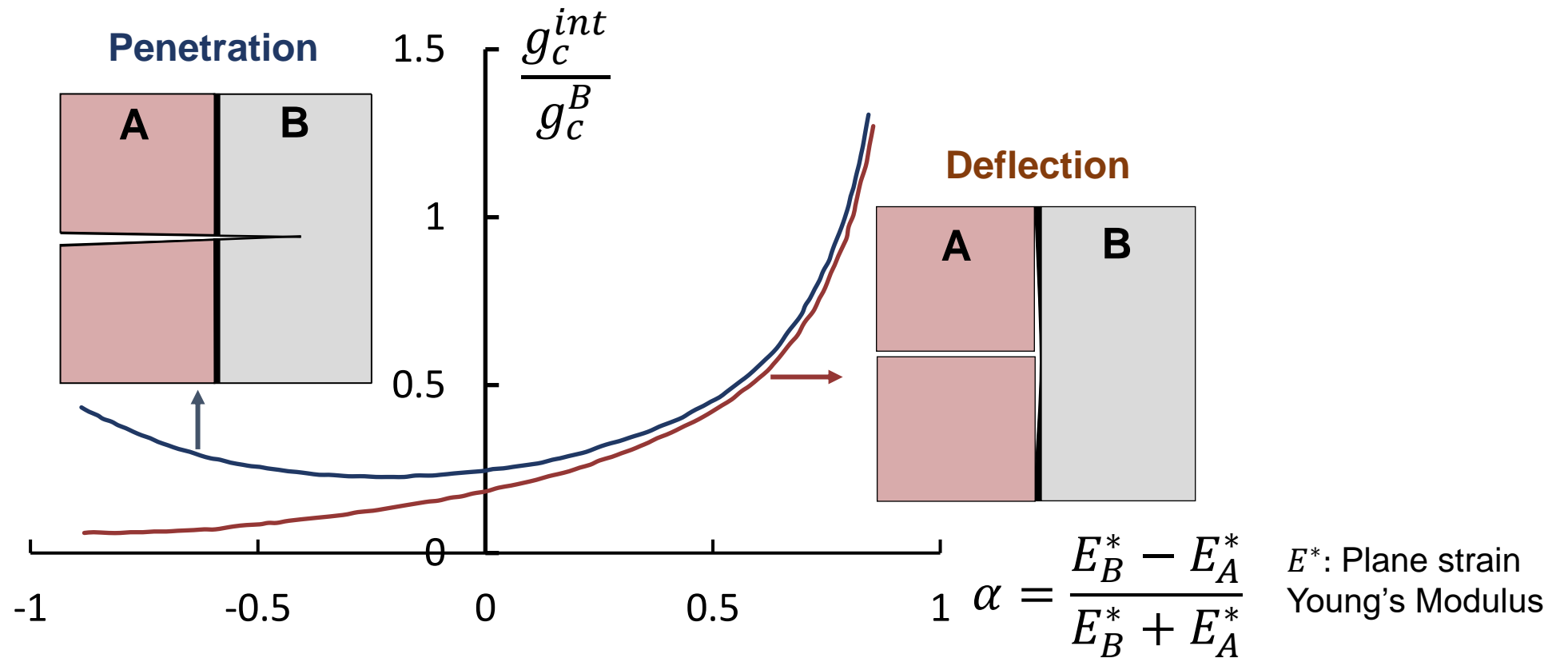
# LEFM shows two predominant crack growth mechanisms in hard-hard bi-layer materials



OR



# Crack propagation mode depends on material and interfacial fracture properties

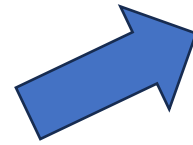
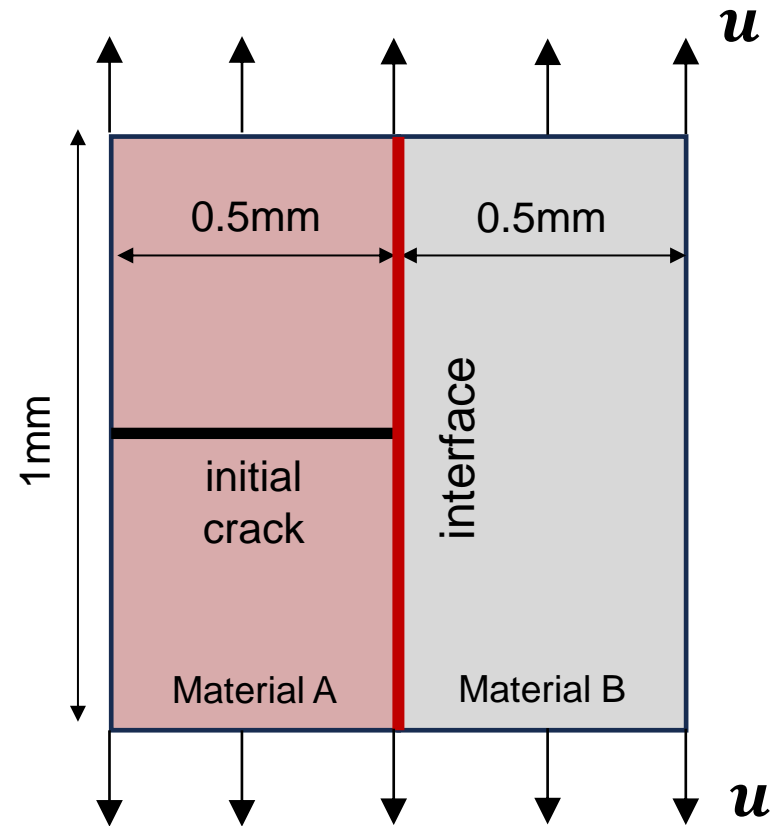


$\alpha$ : Parameter characterizing elastic mismatch of bi-material system [1]

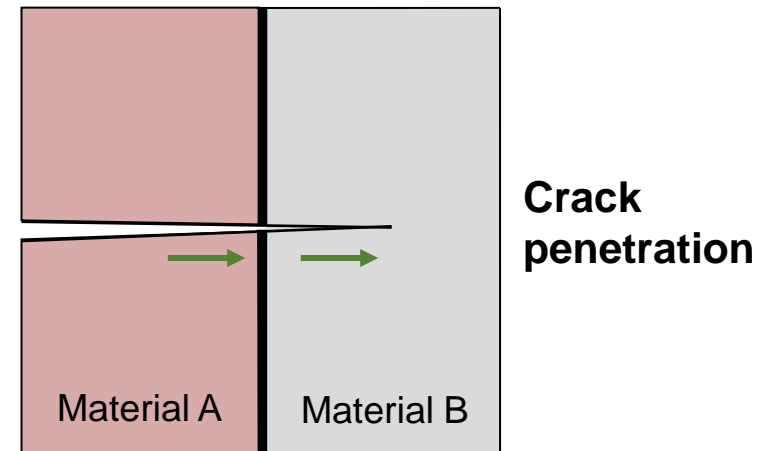
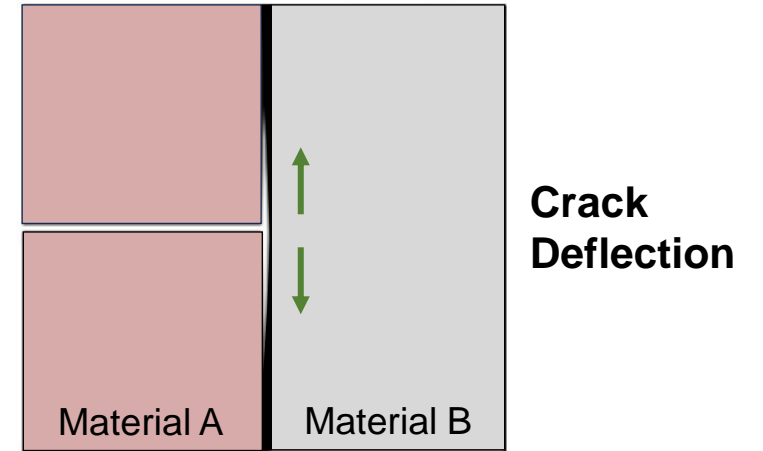
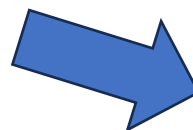
$\frac{g_c^{int}}{g_c^B}$ : Ratio between the fracture energy of the interface and the fracture energy of bulk Material B [1]



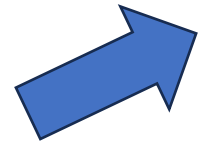
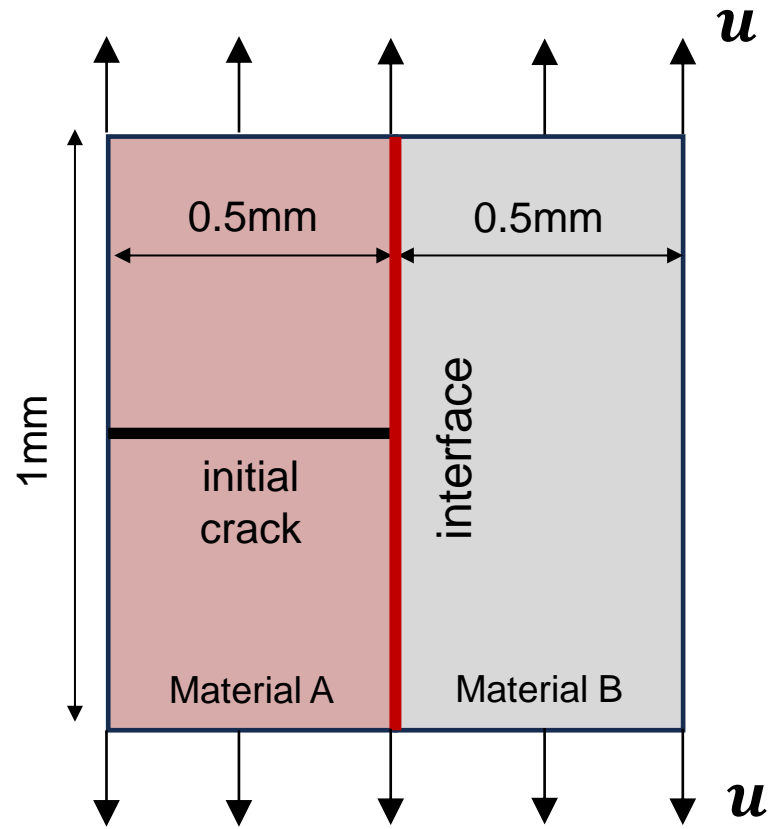
# LEFM shows two predominant crack growth mechanisms in hard-hard bi-layer materials



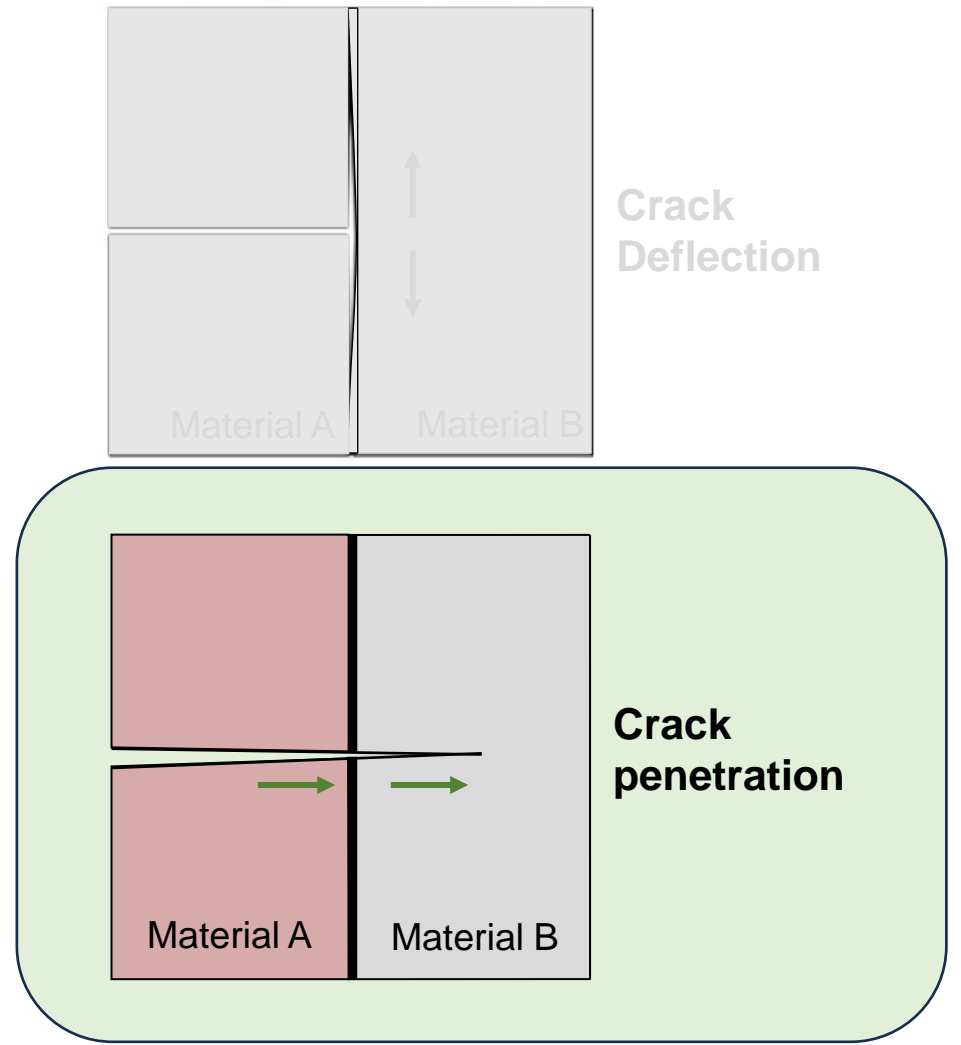
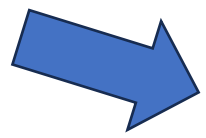
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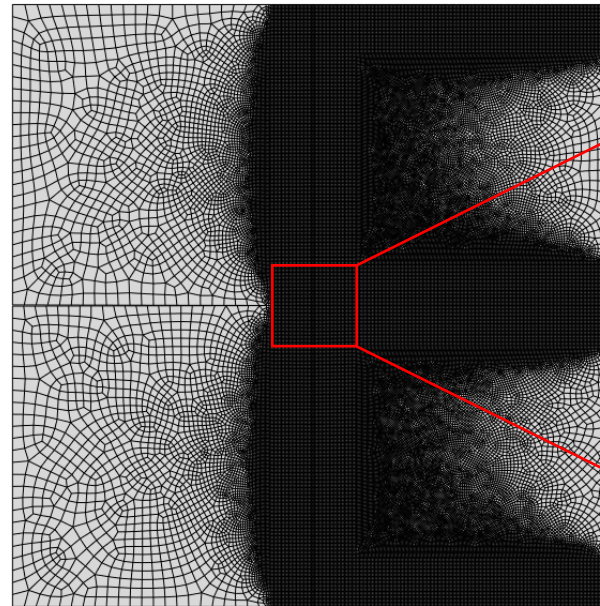
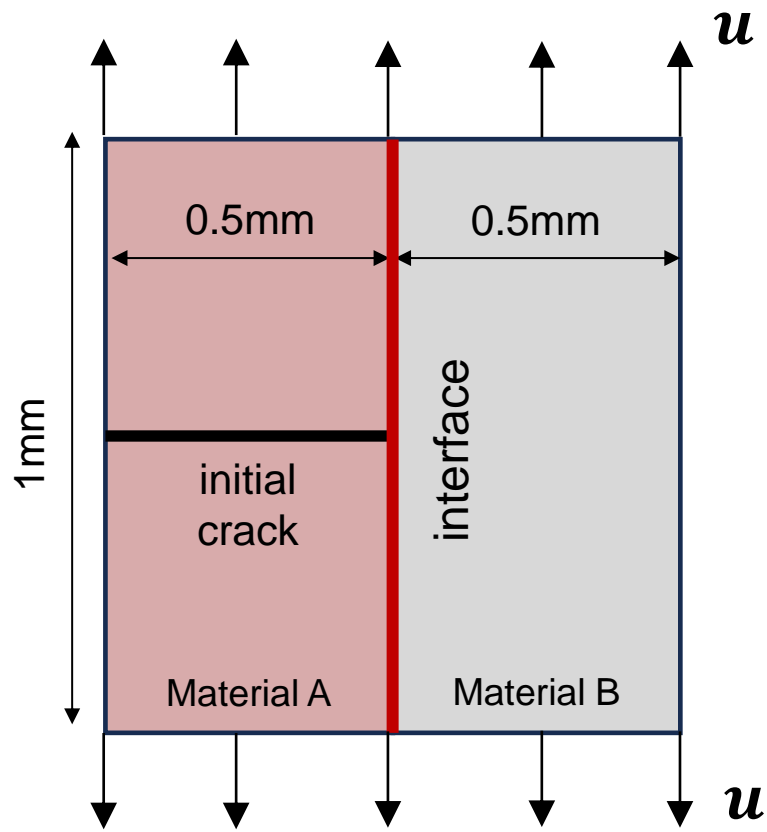
# Crack penetration



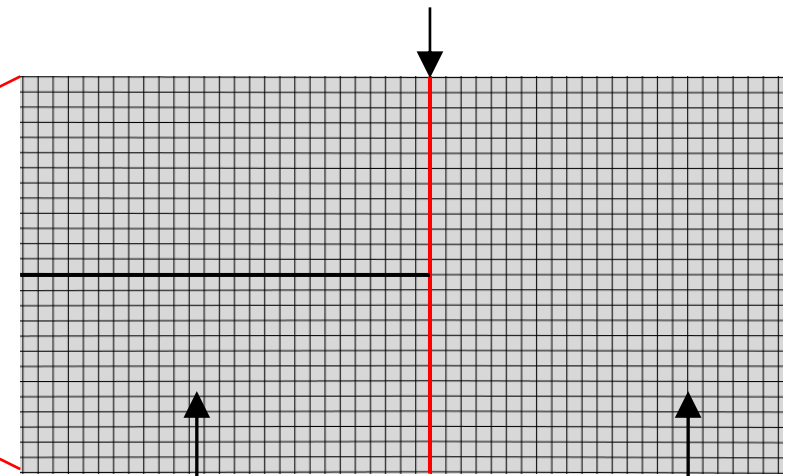
OR



# Zero-thickness cohesive elements used for interface - 4-node quadrilateral plane strain elements used for bulk



**Interface:**  
Zero-thickness cohesive elements

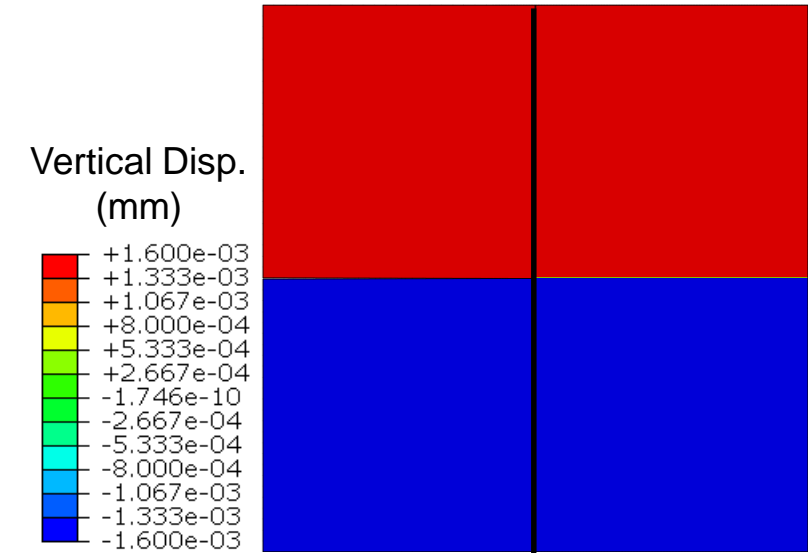
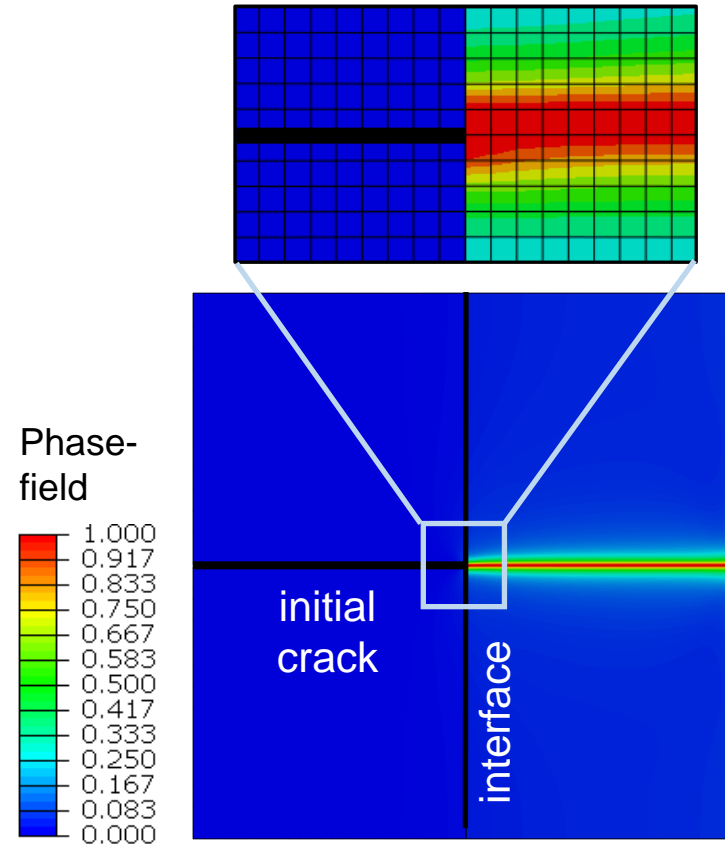
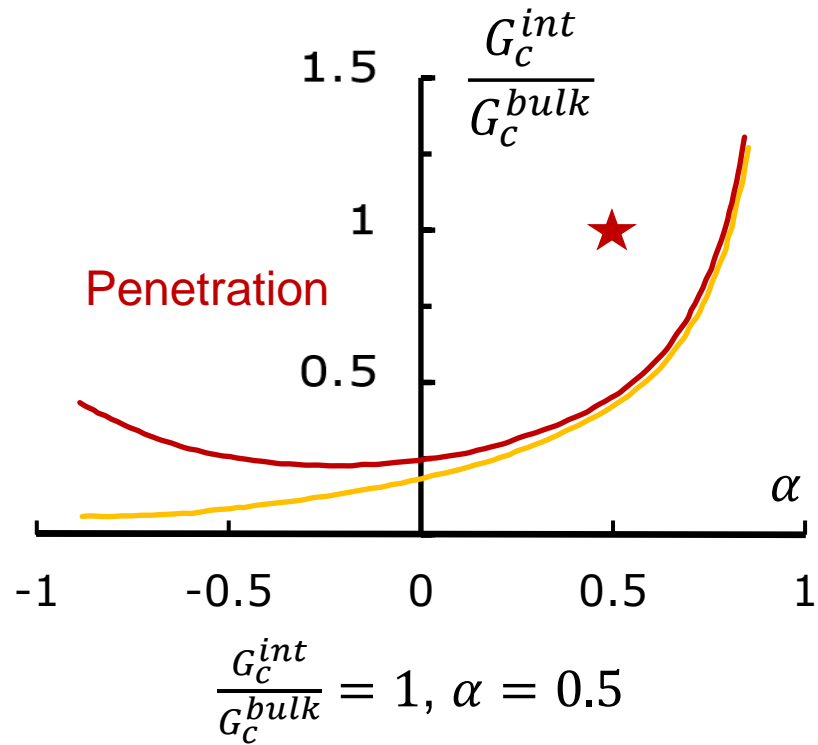


**Bulk:**  
Plane-strain four-node quadrilateral elements

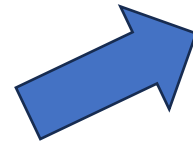
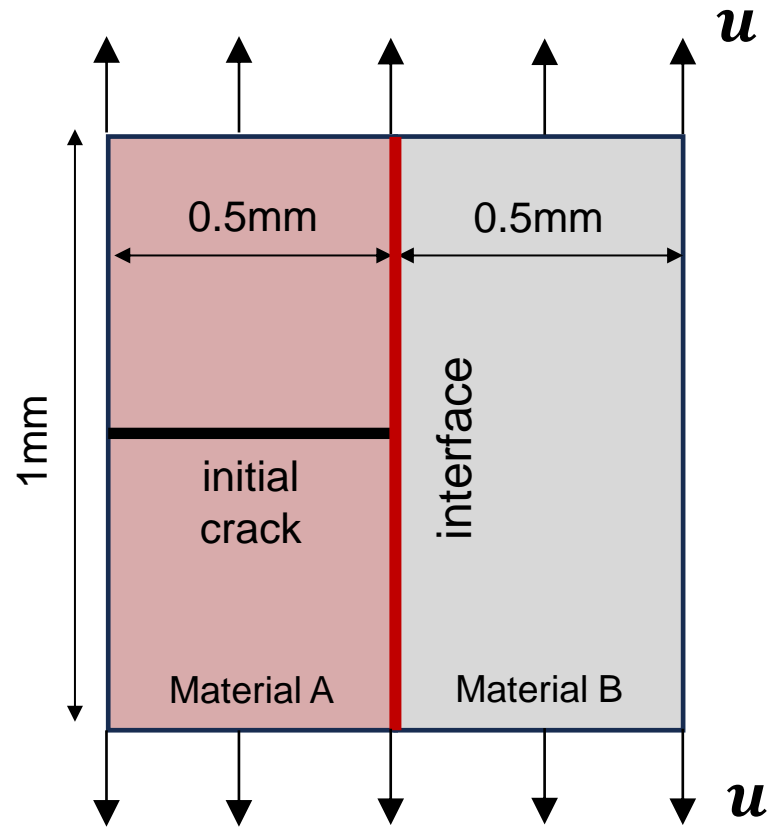




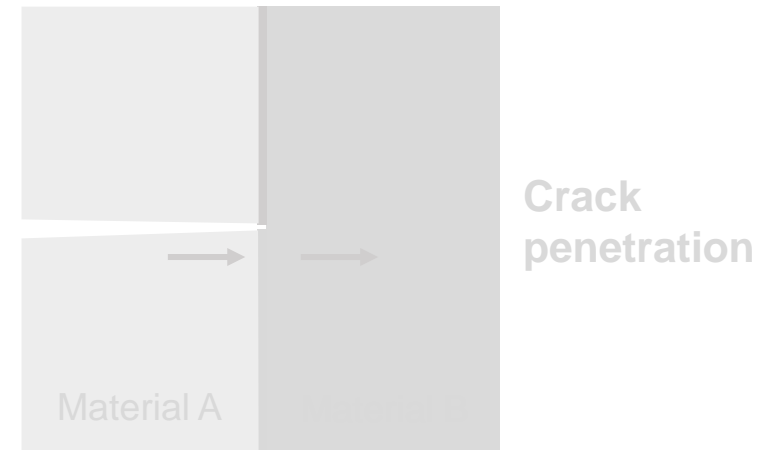
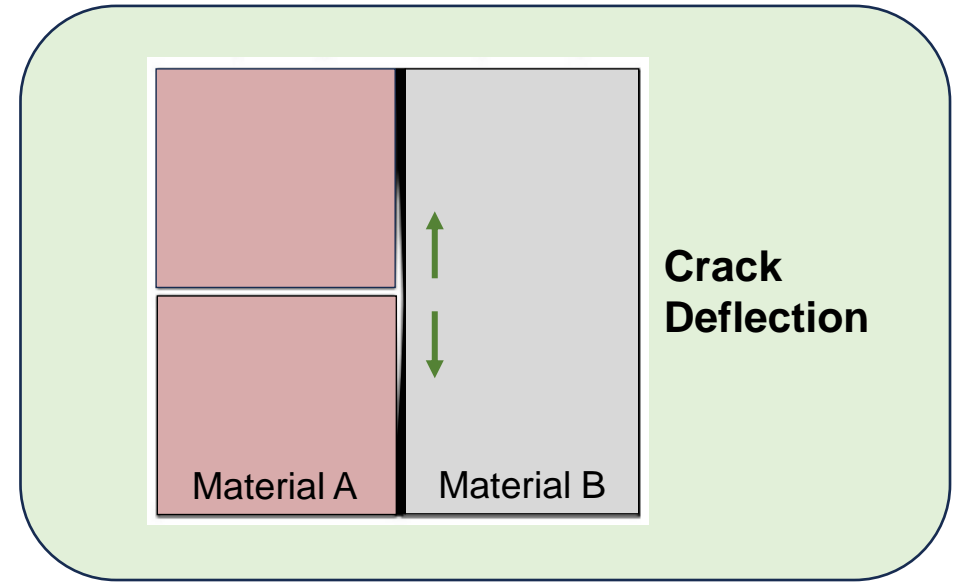
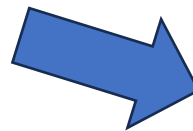
# Simulation predictions



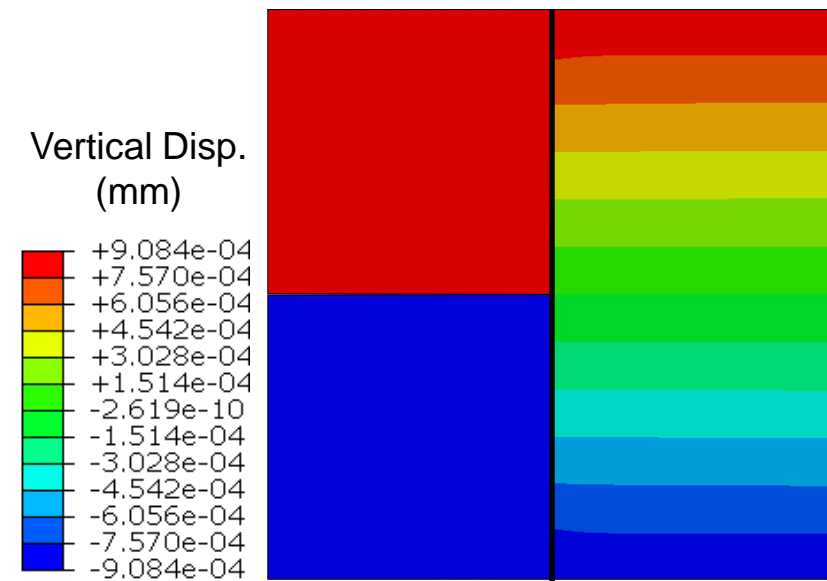
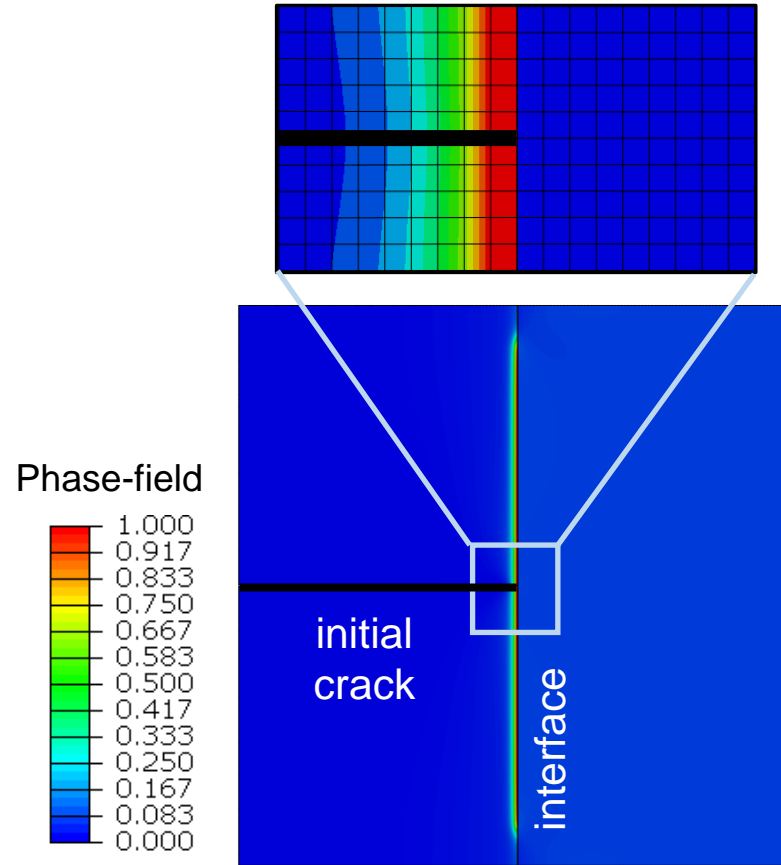
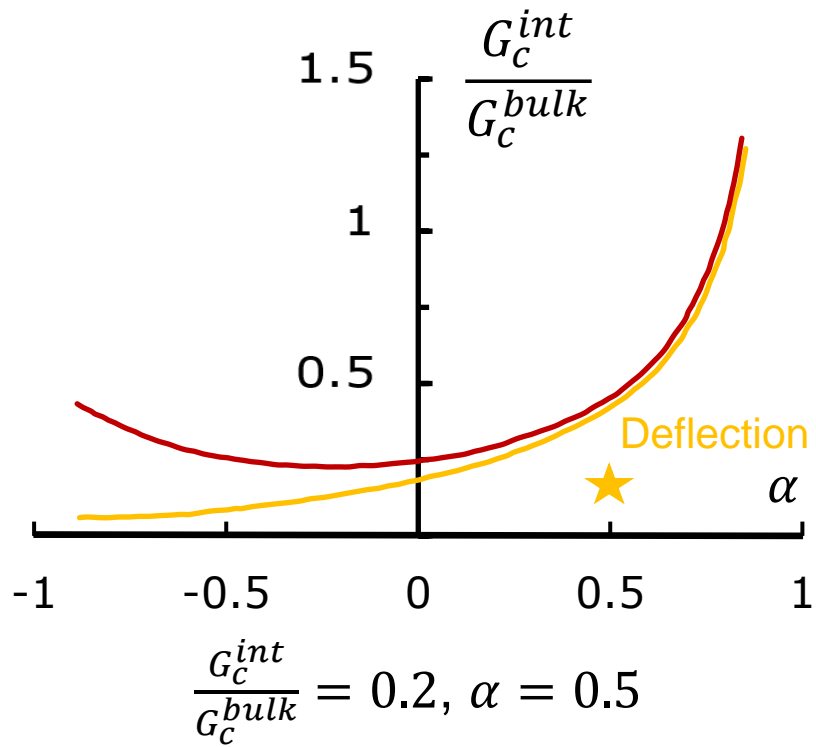
# Crack deflection



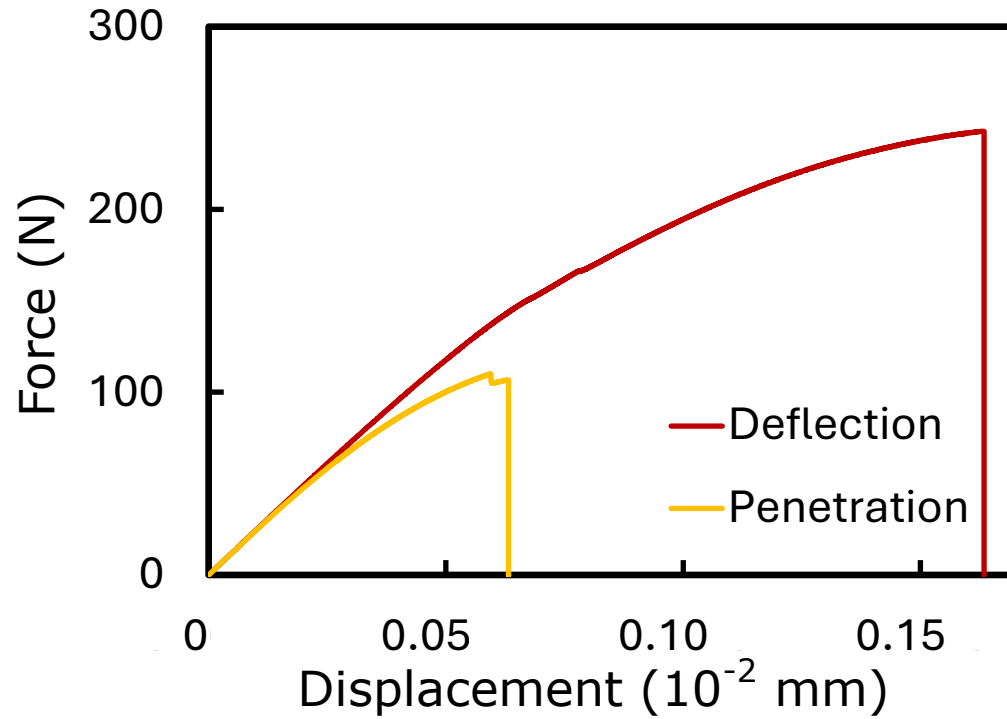
OR



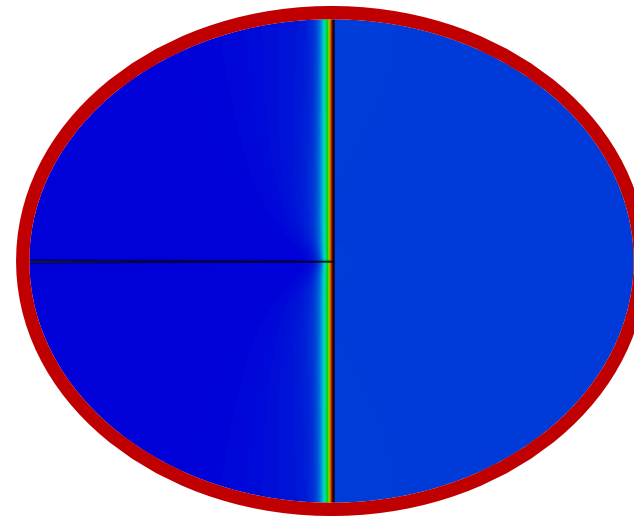
# Simulation predictions



# Overall enhanced performance for the case when crack deflects

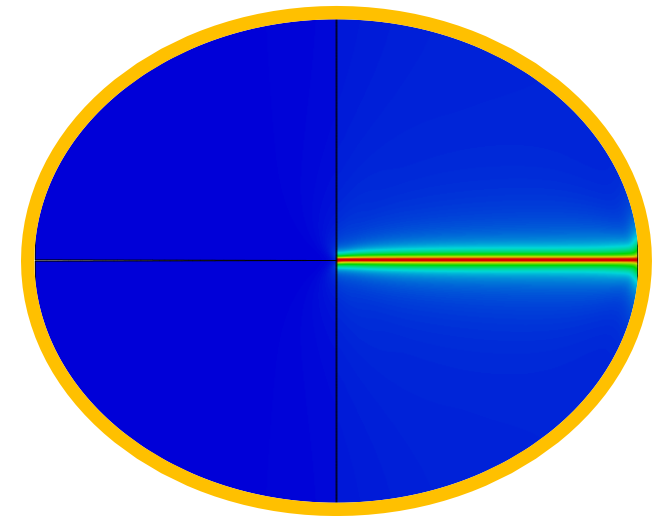


$$\frac{G_c^{int}}{G_c^{bulk}} = 0.2$$
$$\alpha = 0.5$$



Deflection

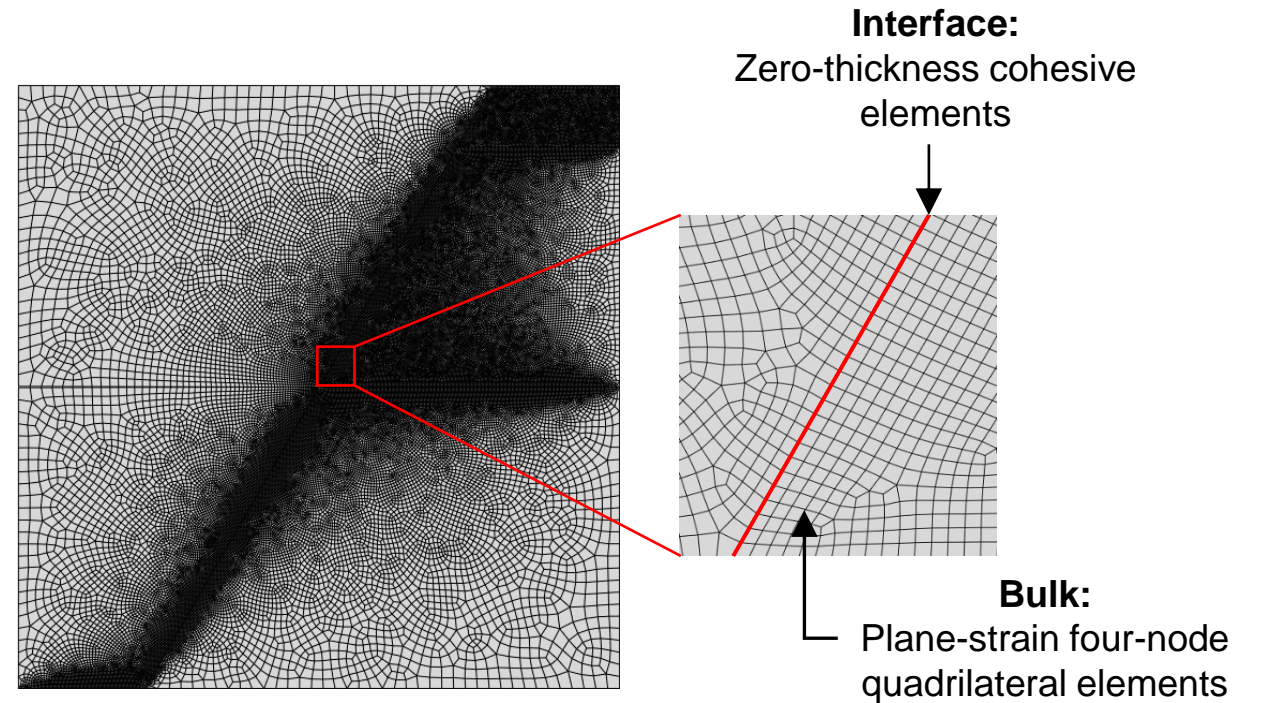
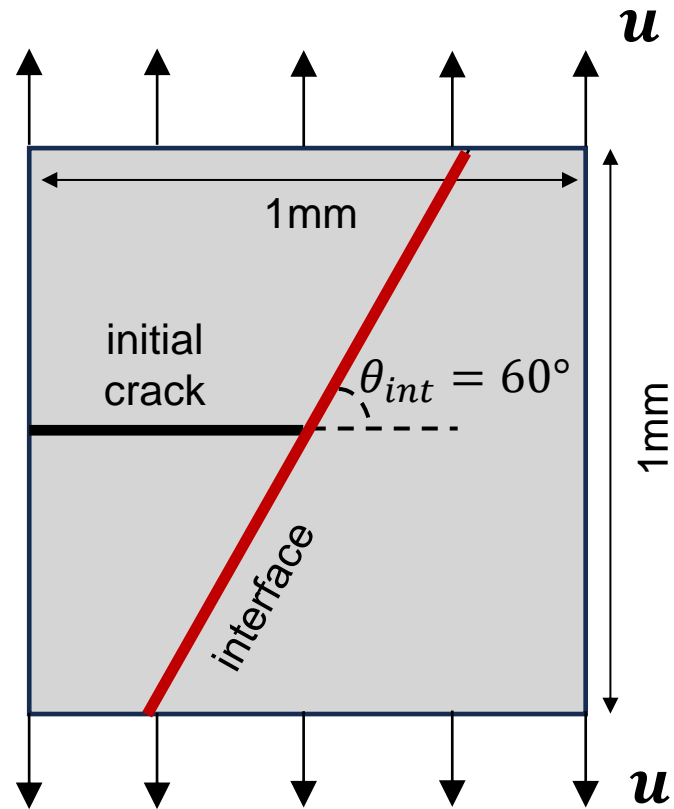
$$\frac{G_c^{int}}{G_c^{bulk}} = 1$$
$$\alpha = 0.5$$



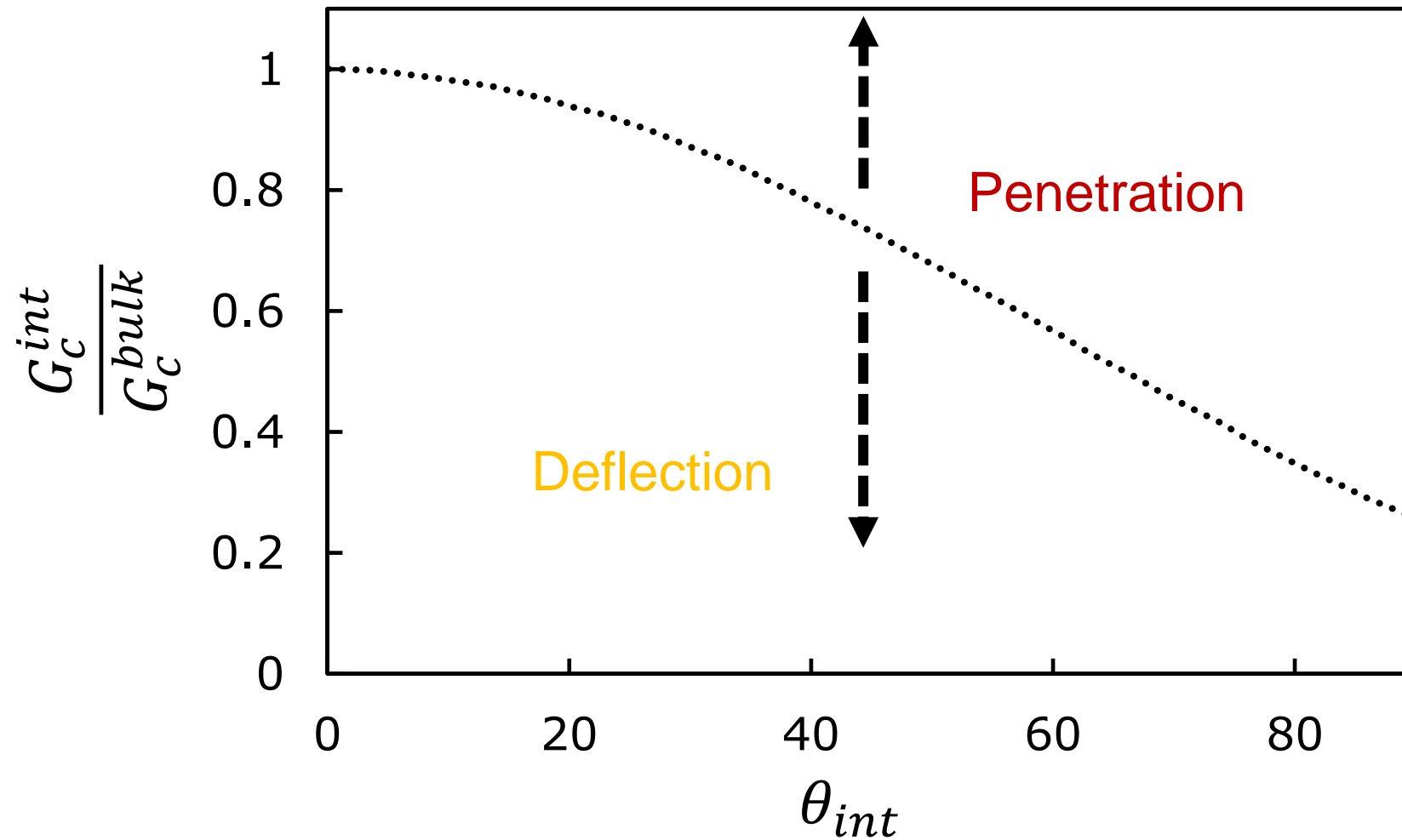
Penetration



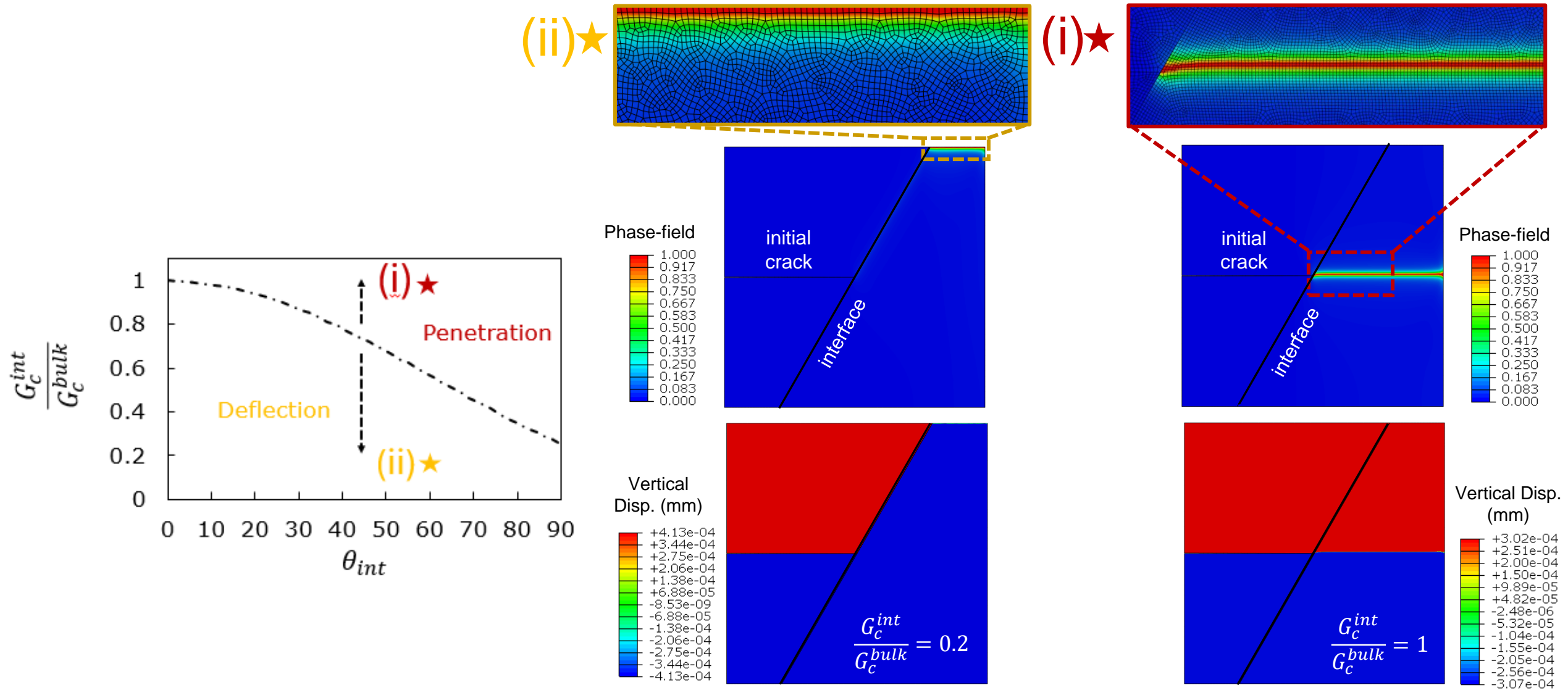
# Crack impinging on an inclined interface



# LEFM theory for the case of a crack impinging on an inclined interface [1]

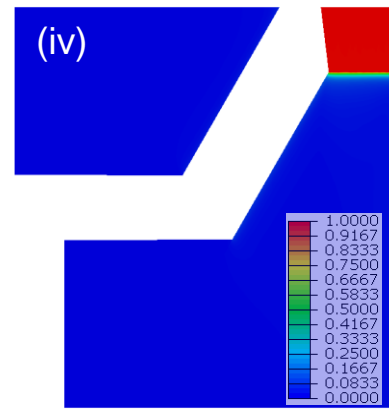
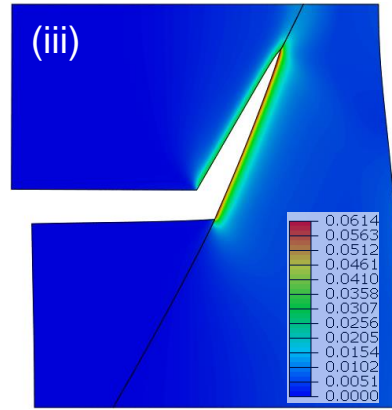
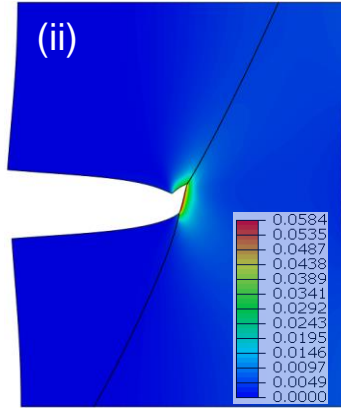
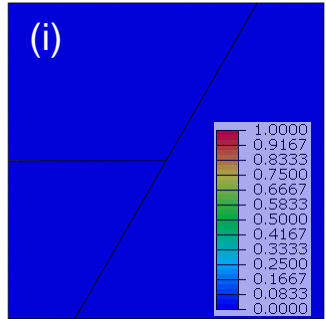


# Framework predictions

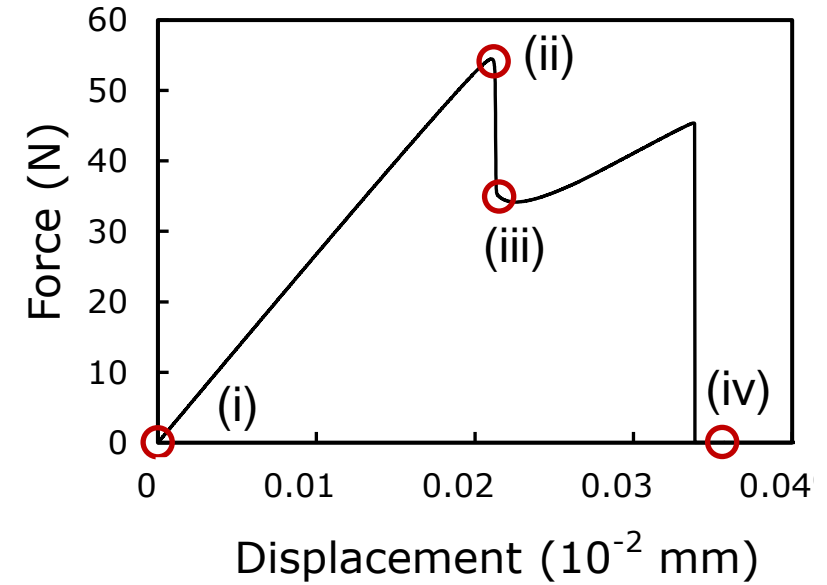
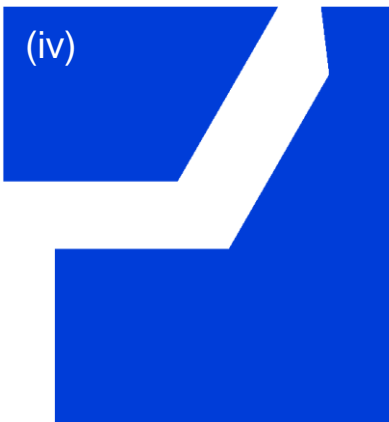
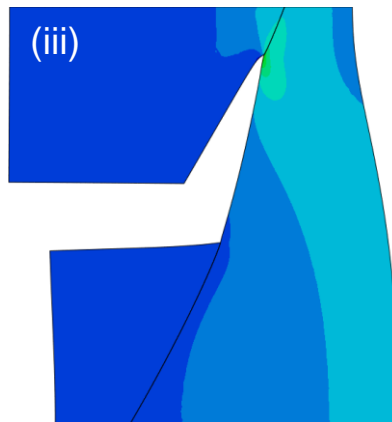
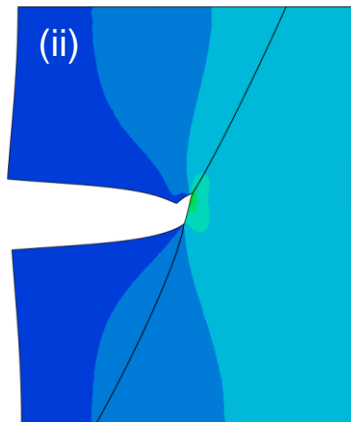
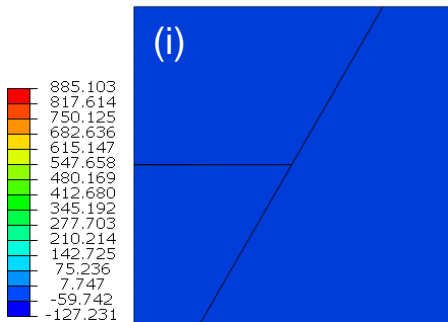


# Crack deflection

Phase-field

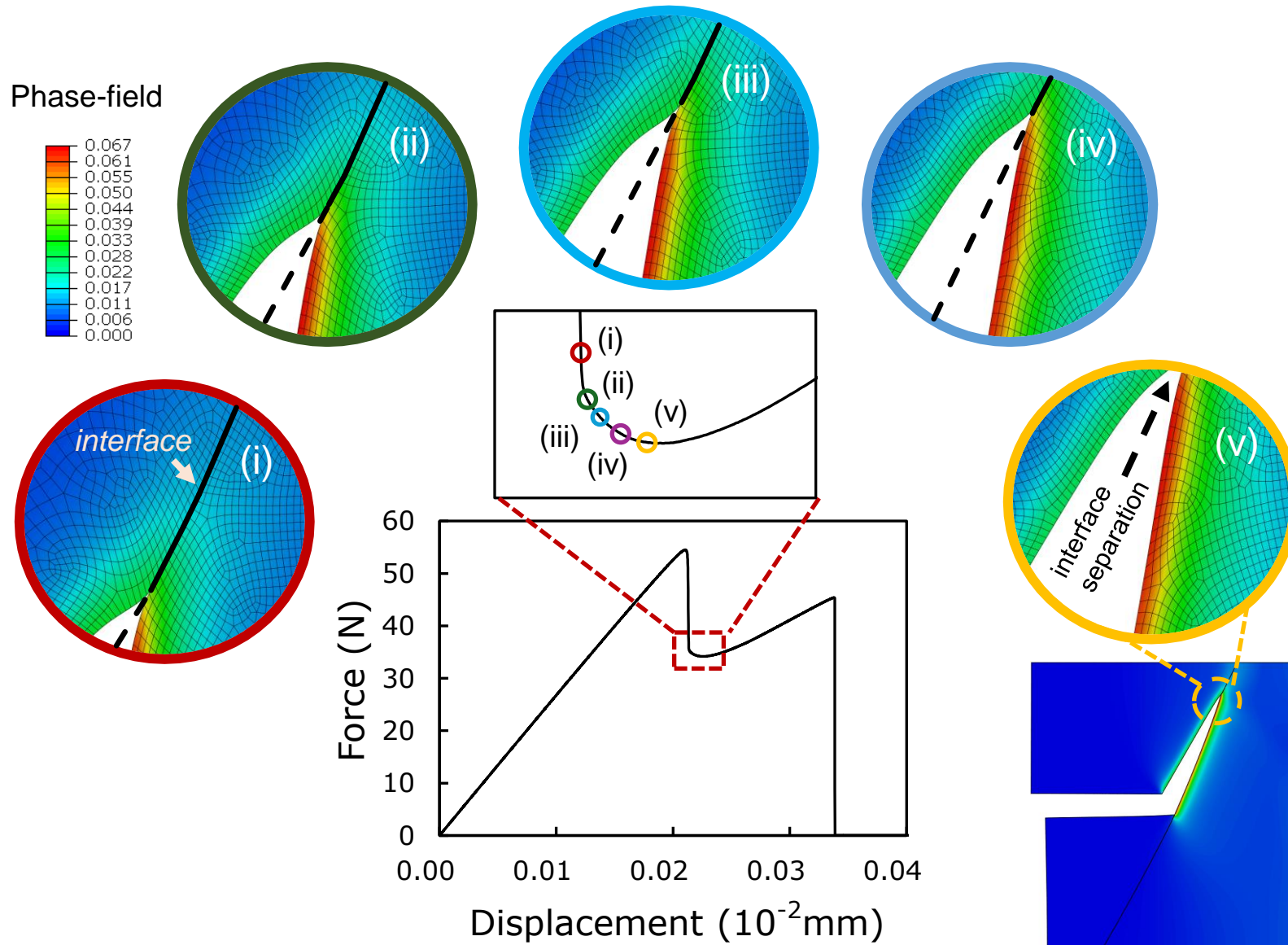


Stress  $S_{22}$  (MPa)

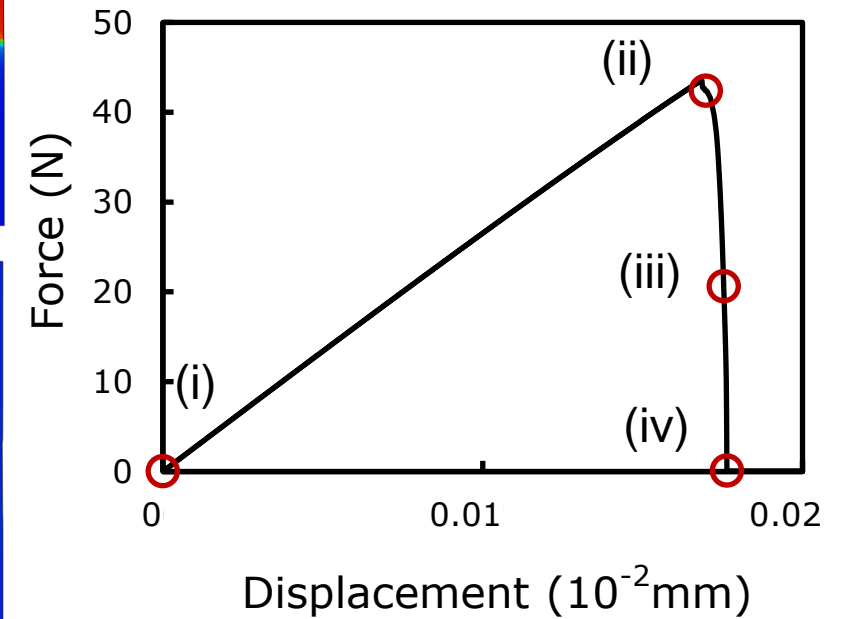
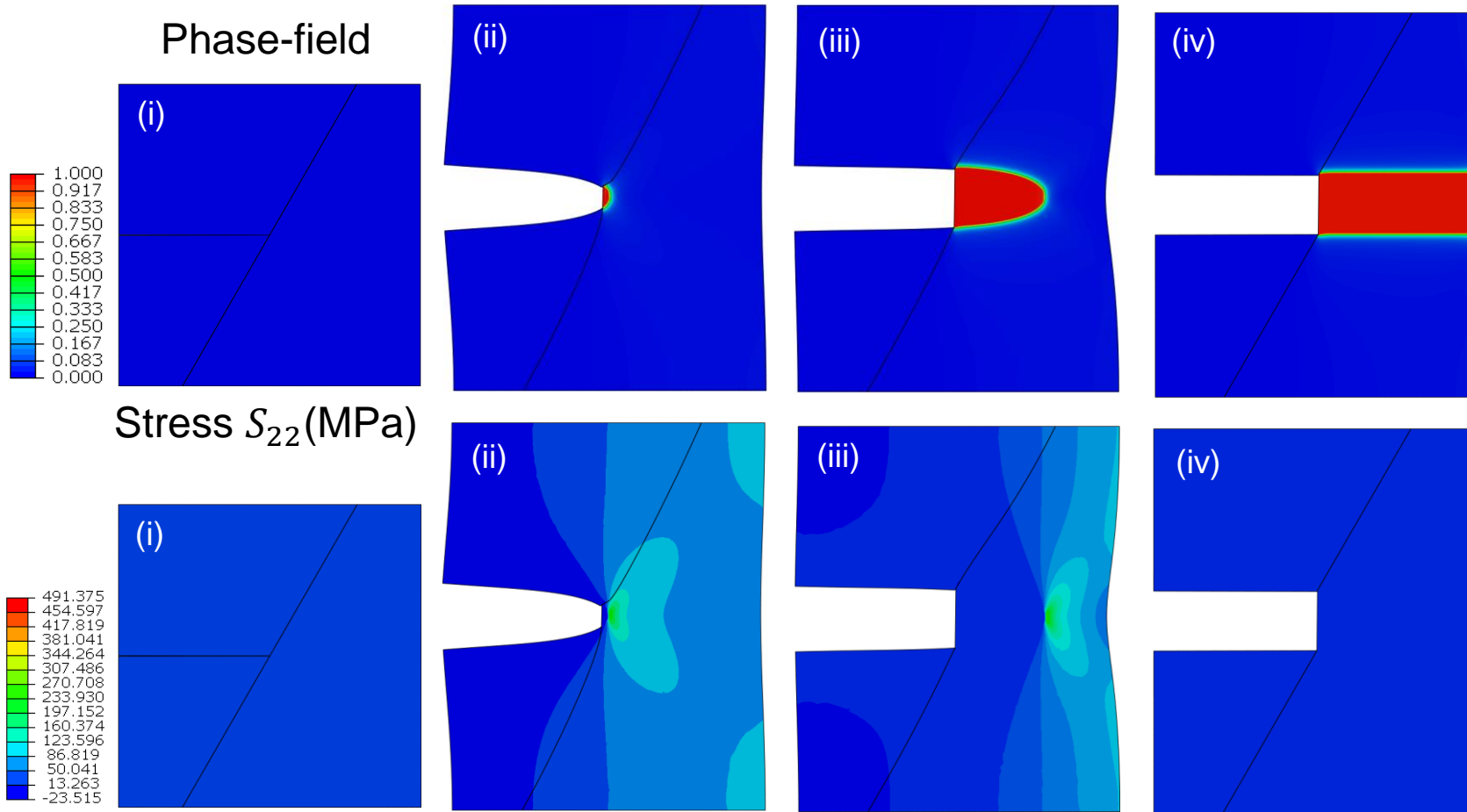




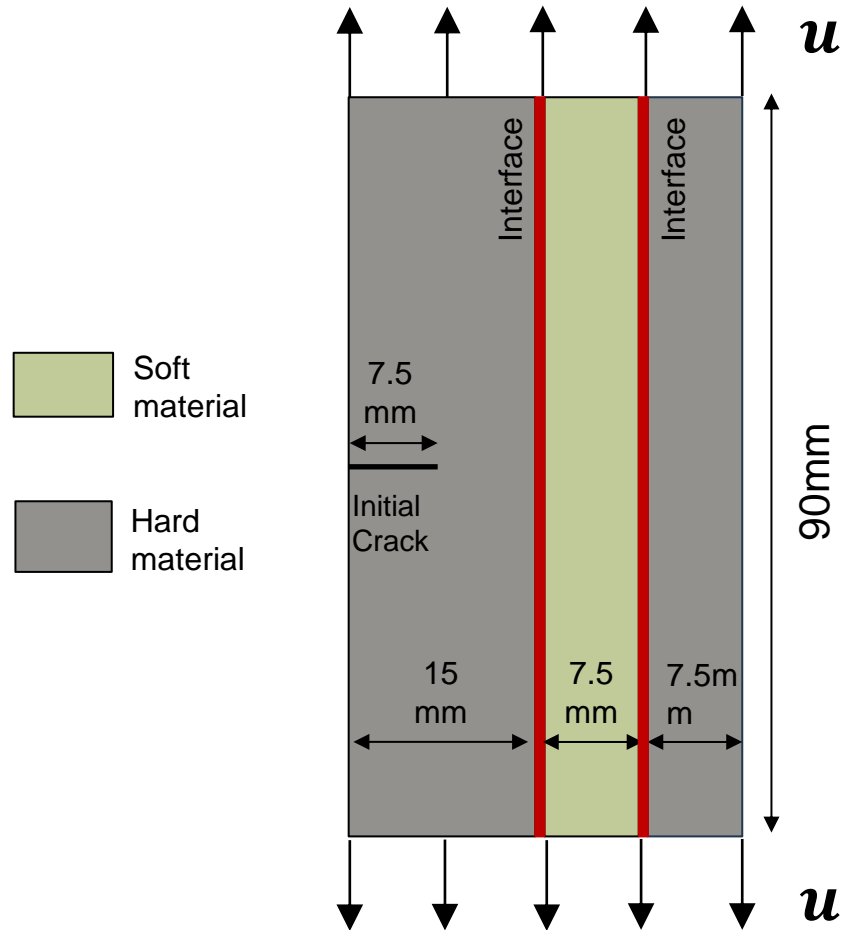
# Interface separation is captured



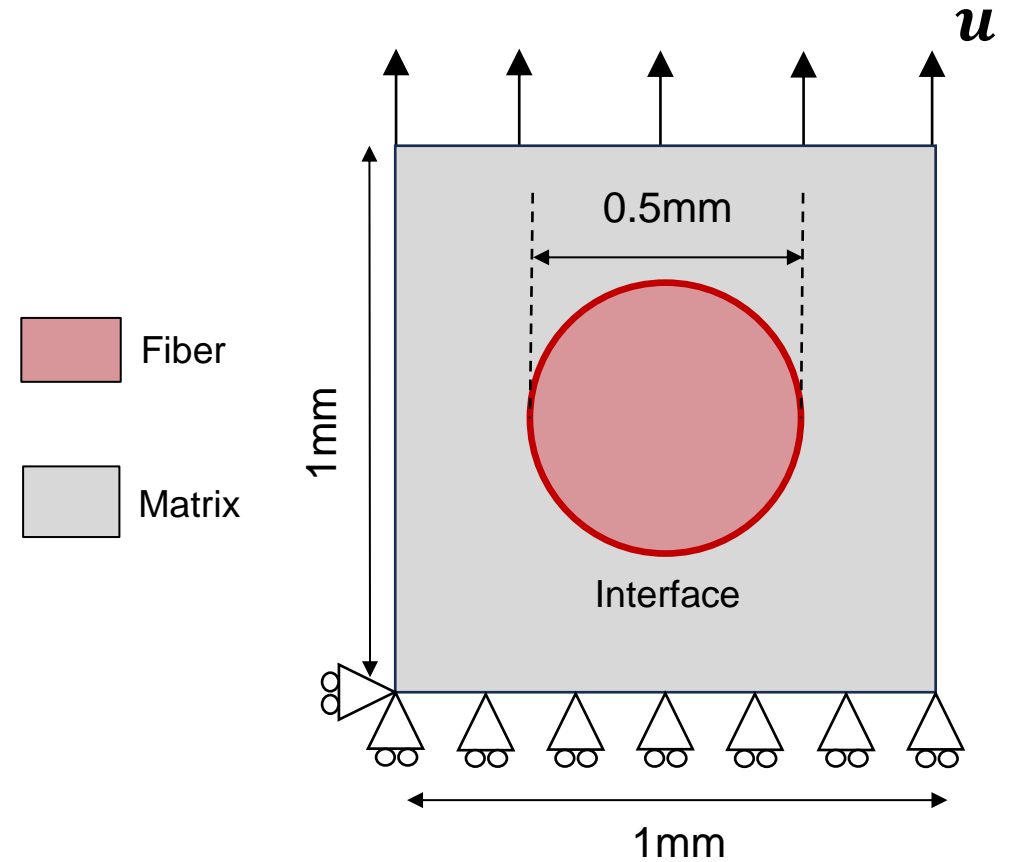
# Crack penetration



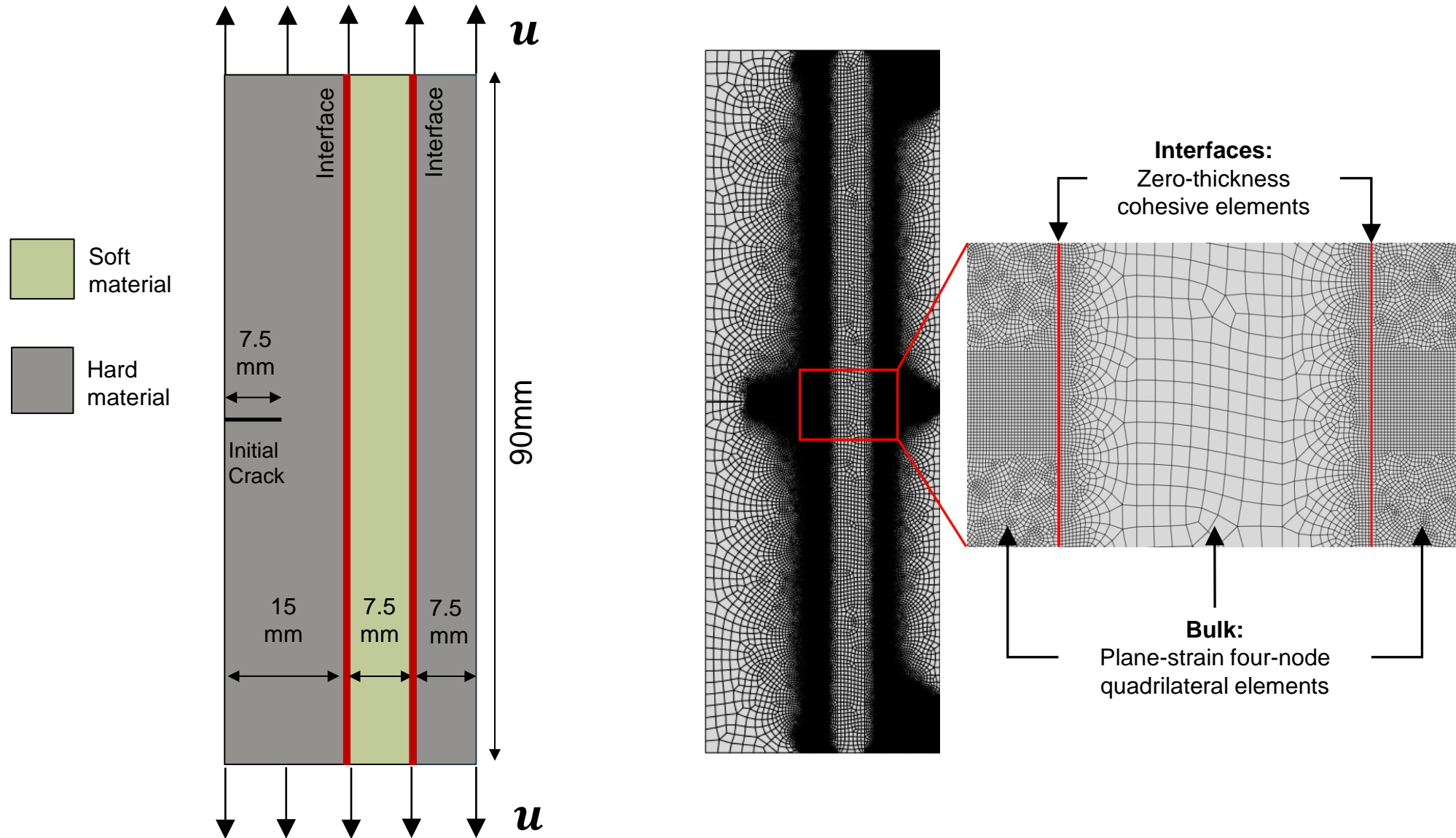
### Case III: hard-soft-hard tri-layer composite with interface perpendicular to initial notch direction



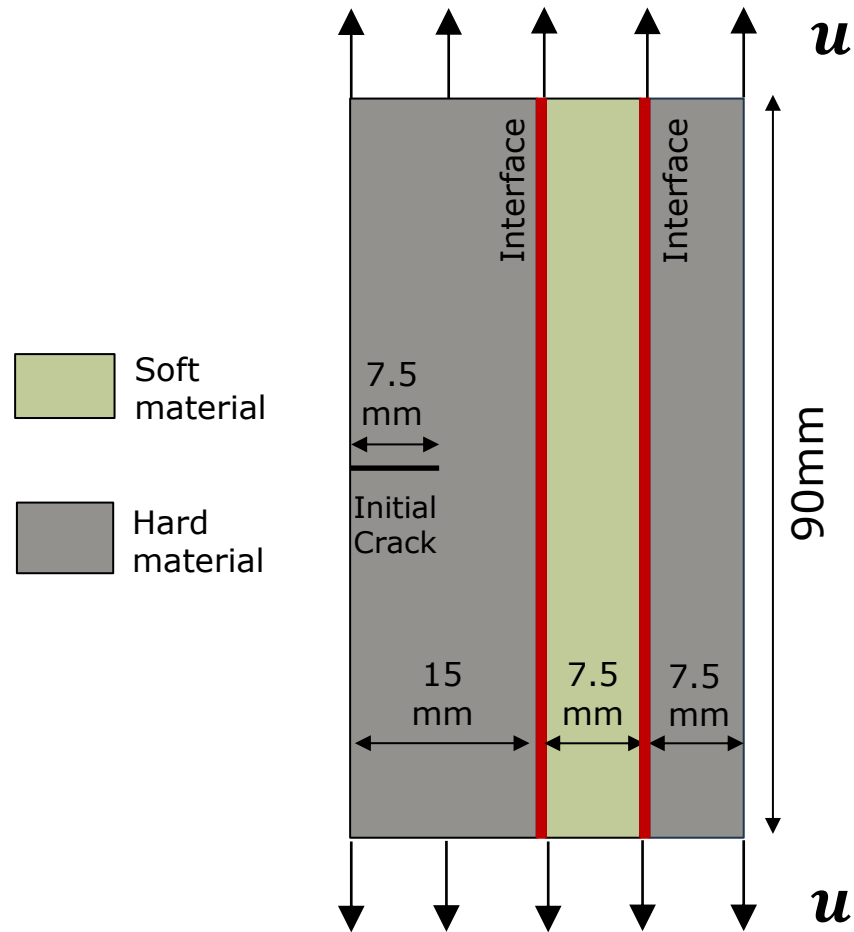
### Case IV: fiber-reinforced matrix composite

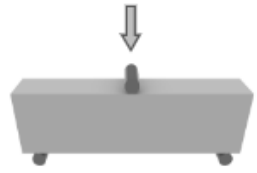

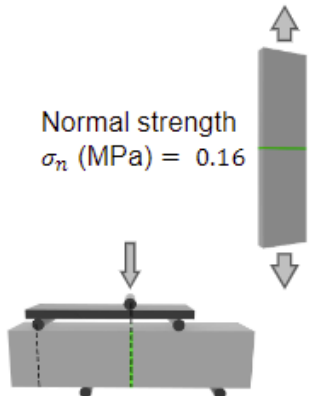
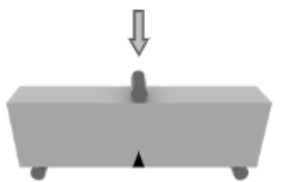
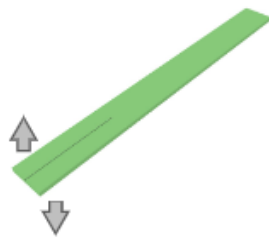
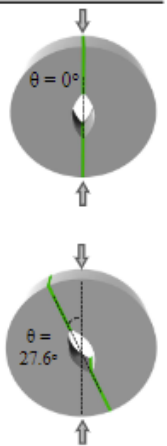


# Zero-thickness cohesive elements used for interface - 4-node quadrilateral plane strain elements used for bulk



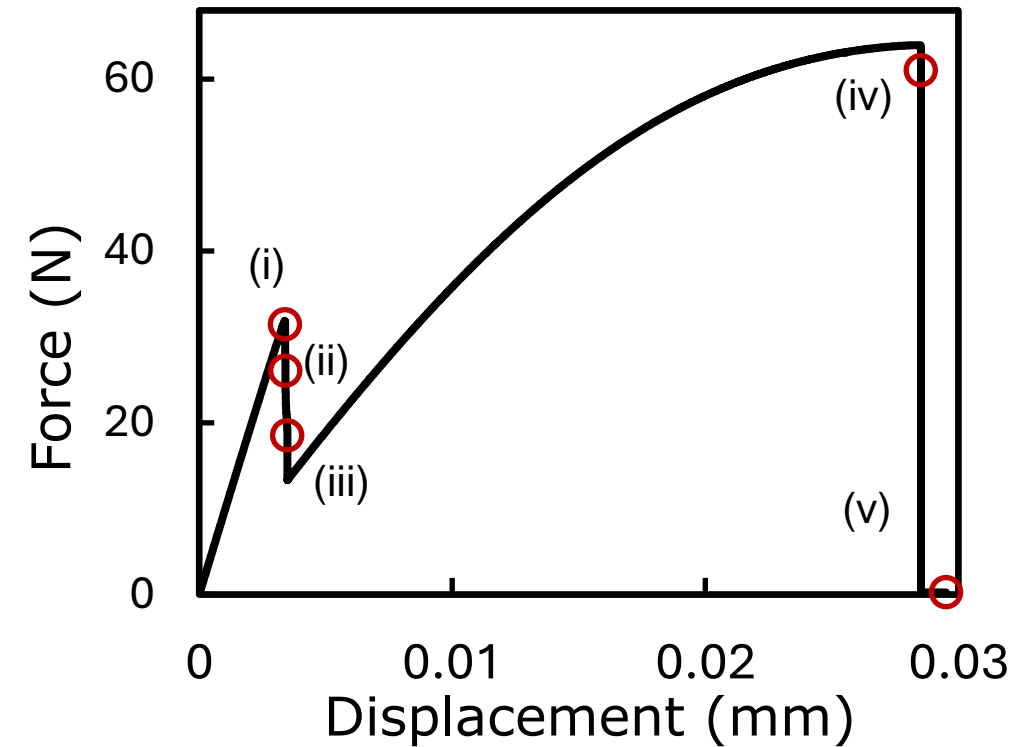
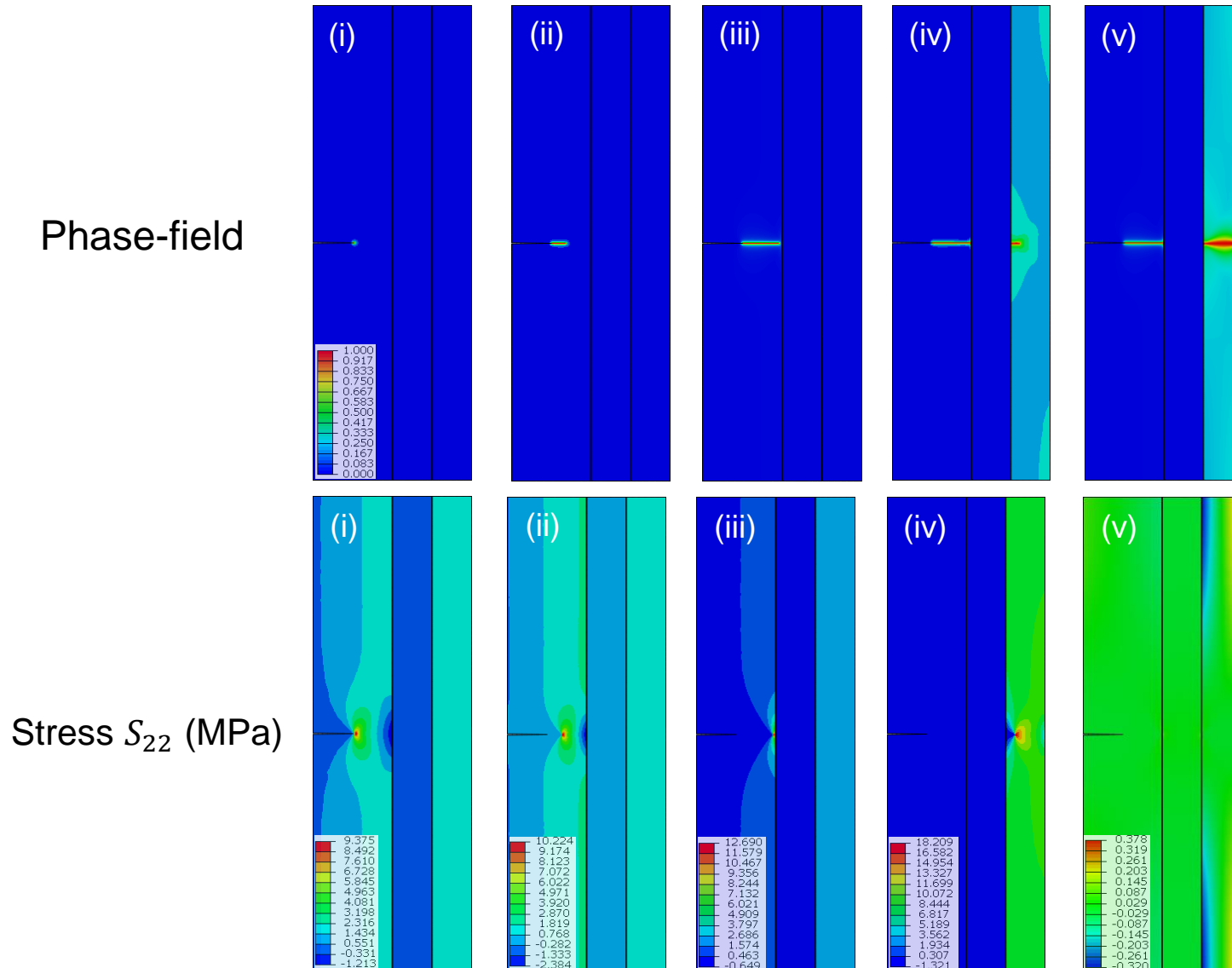
# Material properties were determined using specific mechanical characterization tests



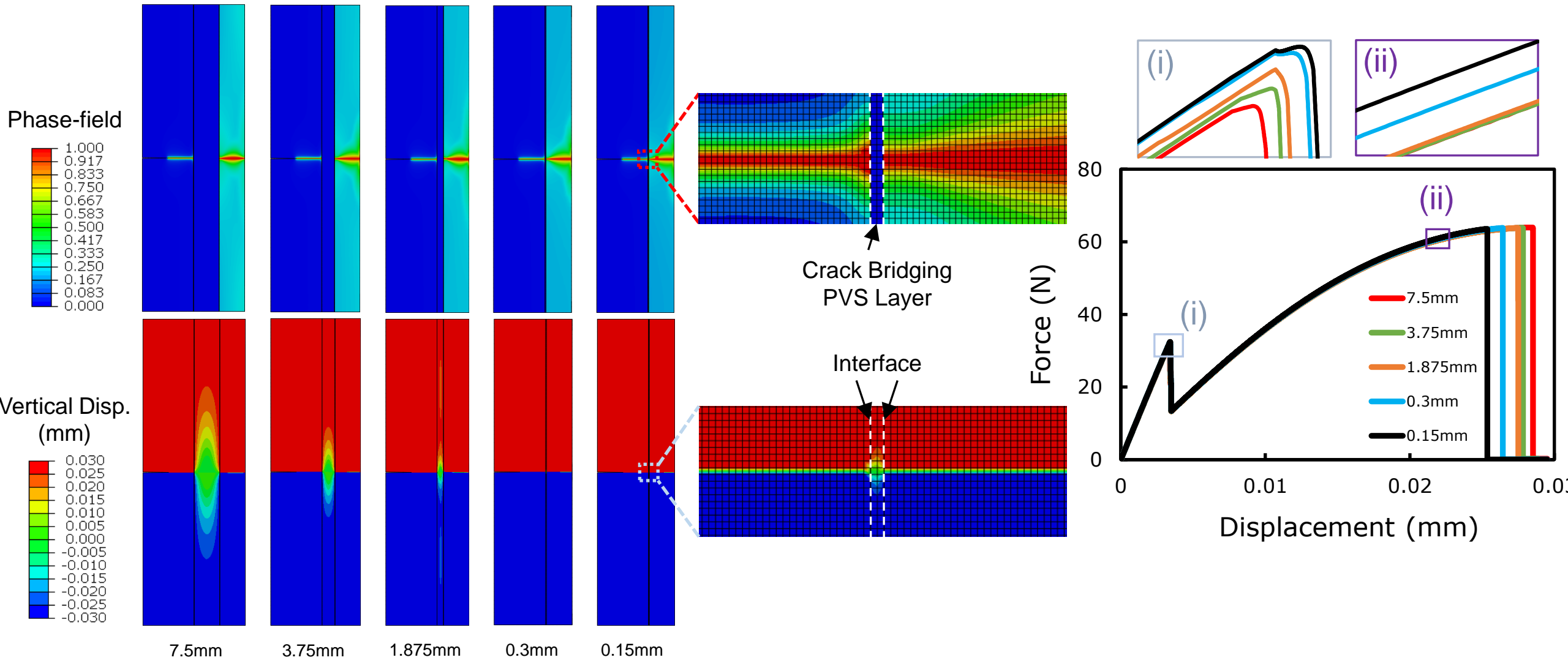
	Hardened Cement Paste	PVS	Interface
Mechanical properties	 Modulus of rupture $\sigma_c$ (MPa) = 3.36 Modulus of elasticity $E_c$ (MPa) = $2.2e^4$ Poisson's ratio $\nu_c = 0.22$	 Tensile strength $\sigma_p$ (MPa) = 1.06 Rubber modulus $\mu_p$ (MPa) = 0.4 Poisson's ratio $\nu_p = 0.49$	 Normal strength $\sigma_n$ (MPa) = 0.16 Tangential strength $\sigma_t$ (MPa) = 0.29
Fracture properties	 Fracture toughness $G_{c_c}$ (N/mm) = $4.47e^{-3}$	 Fracture toughness $G_{c_p}$ (N/mm) = 1.29	 Mode-I Fracture toughness $G_{c_I}$ (N/mm) = 1.23 Mode-II Fracture toughness $G_{c_{II}}$ (N/mm) = 1.29



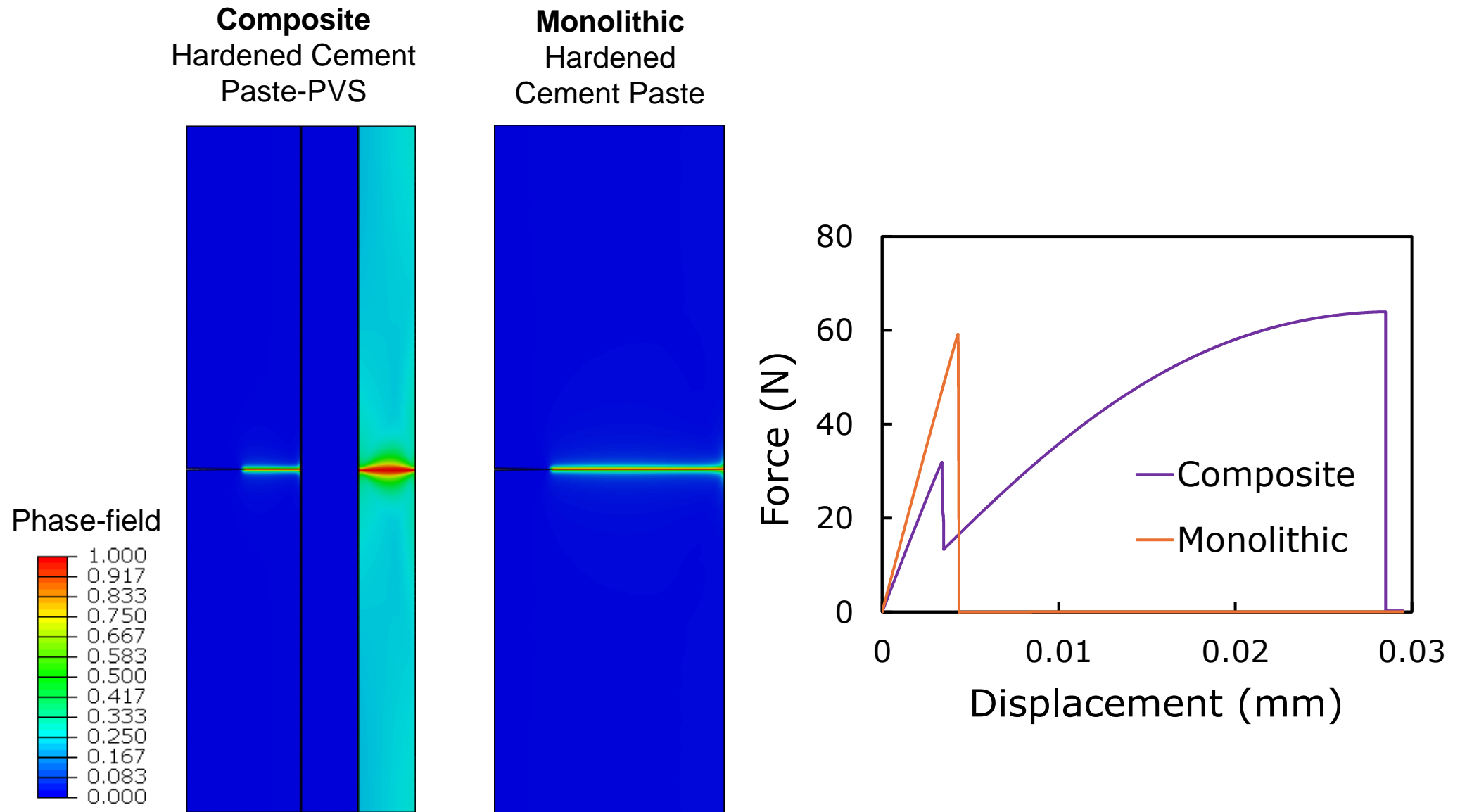
# Crack propagation mechanism in tri-layer hard-soft-hard composite



# Effect of thickness on overall performance



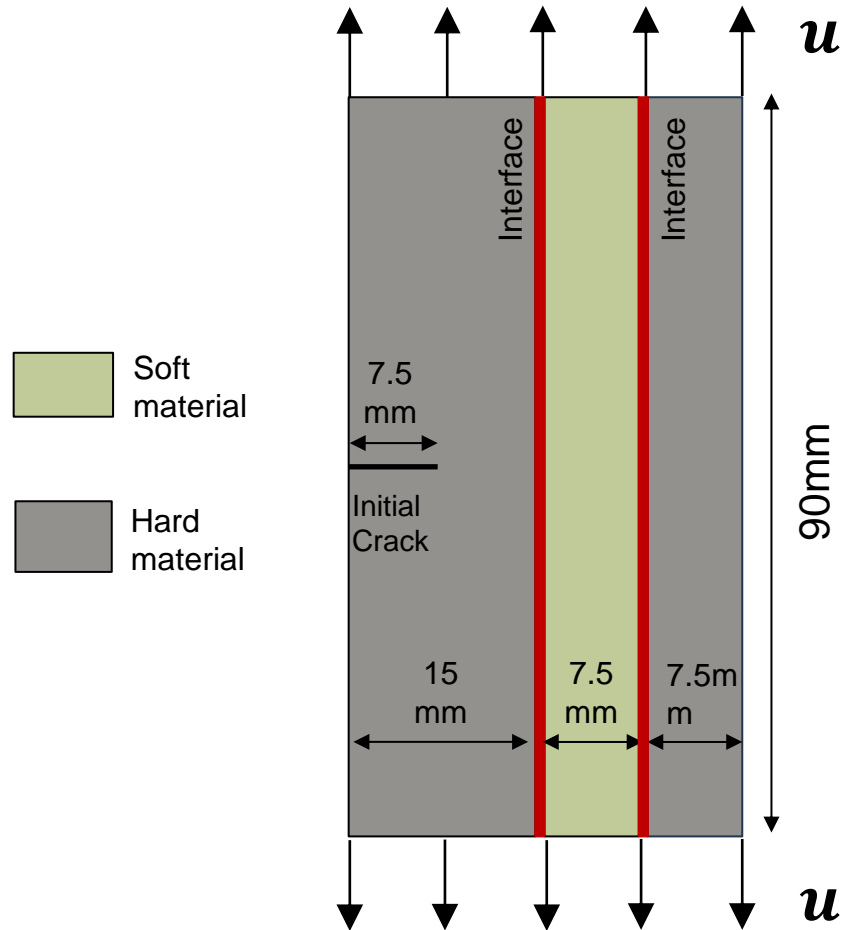
# Hardened cement-PVS composite shows significant increase in toughness vs. monolithic





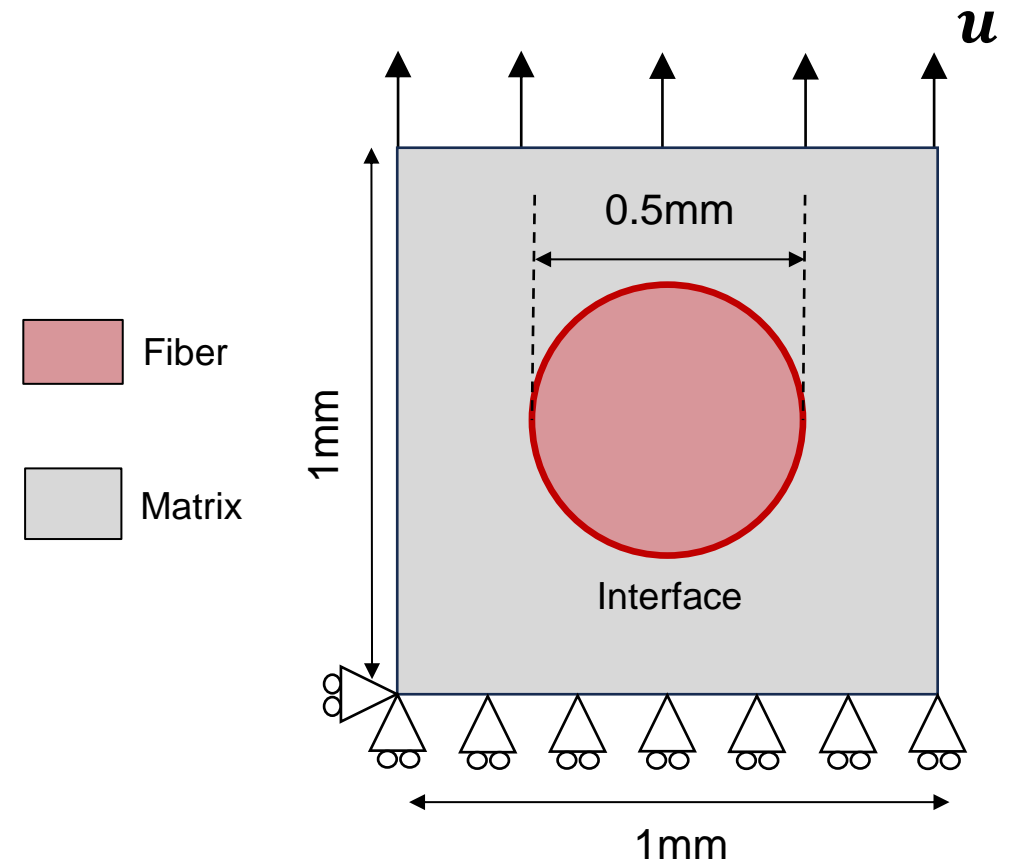
### Case I: hard-hard bi-layer composite

To illustrate the capability of the framework in capturing deflection and penetration

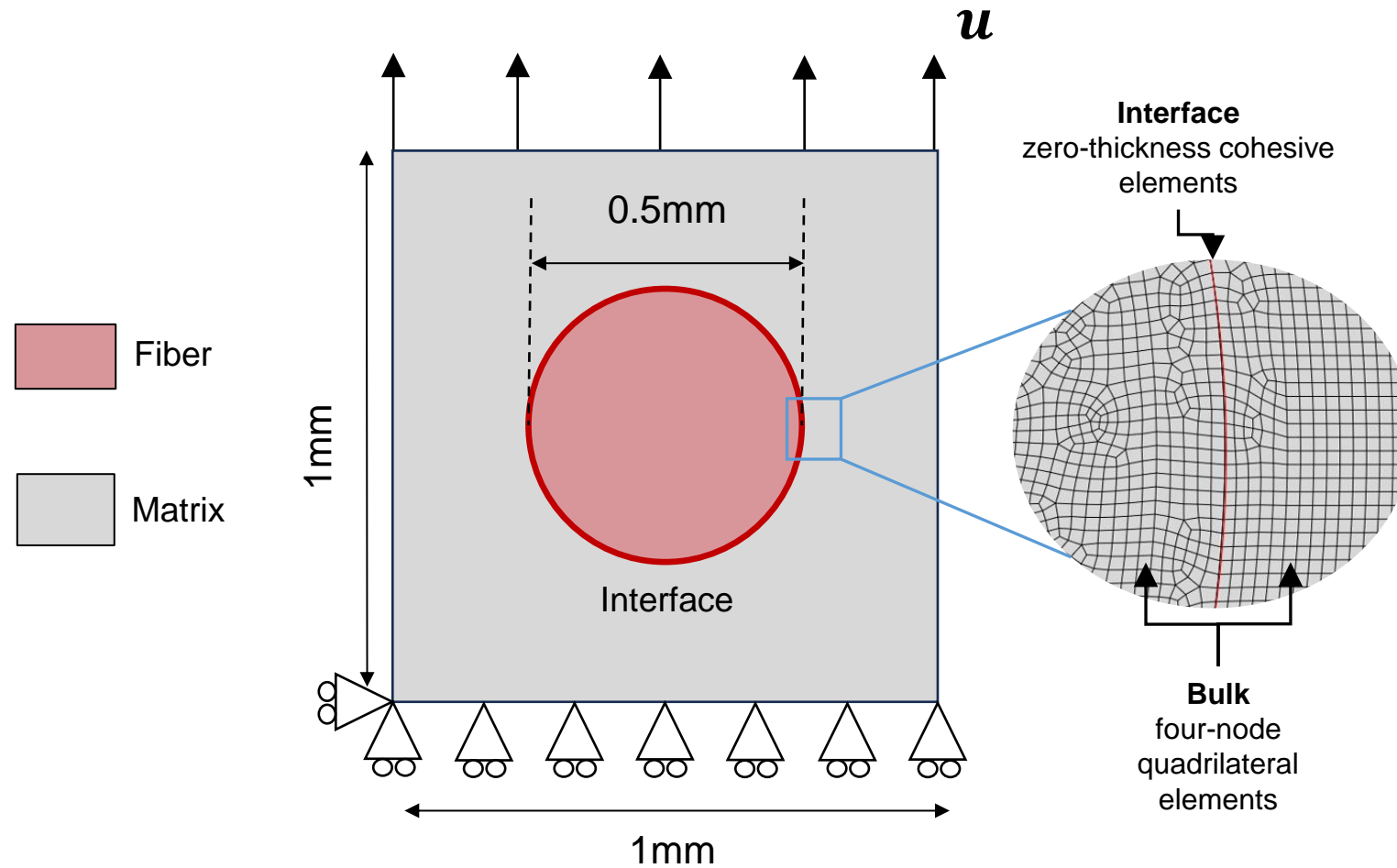


### Case II: hard-soft-hard tri-layer composite

To examine toughening mechanisms achieved by exploiting compliancy of soft material



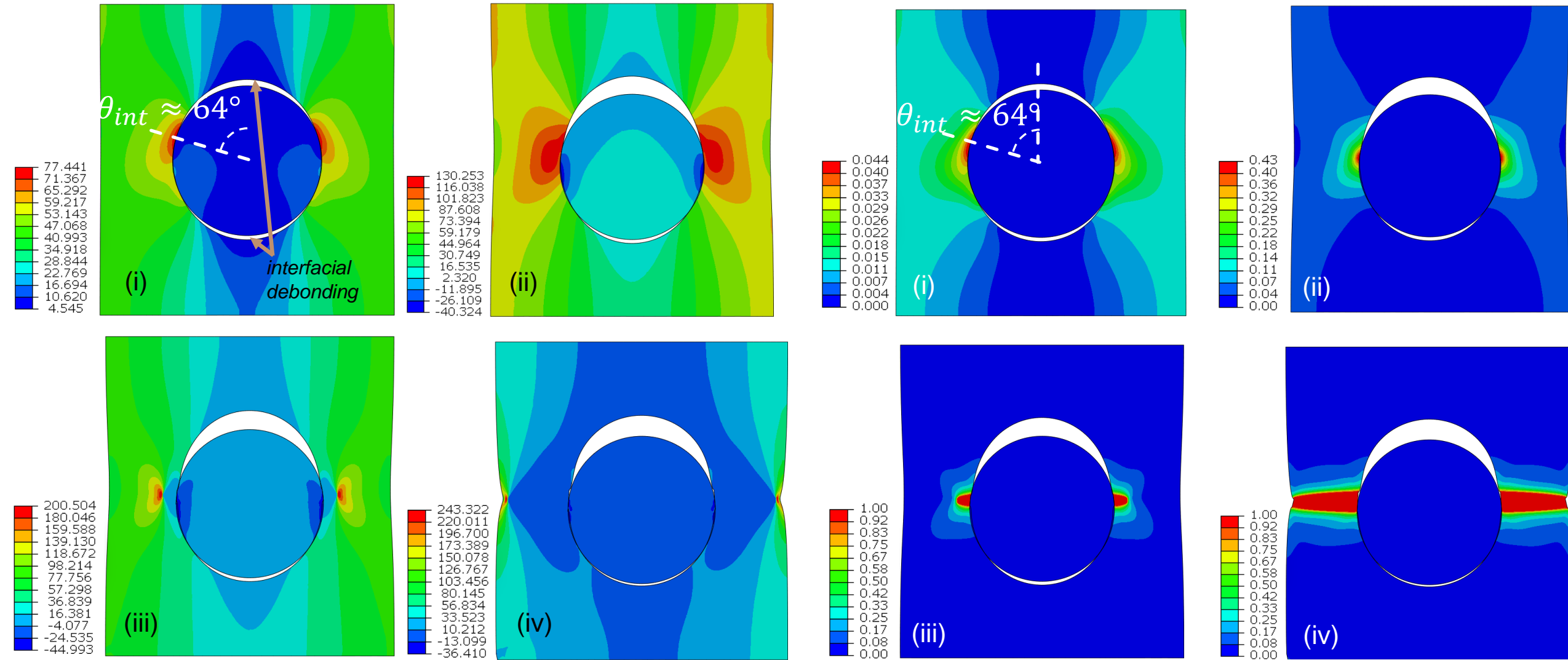
# Zero-thickness cohesive elements used for interface - 4-node quadrilateral plane strain elements used for bulk



# Framework predictions

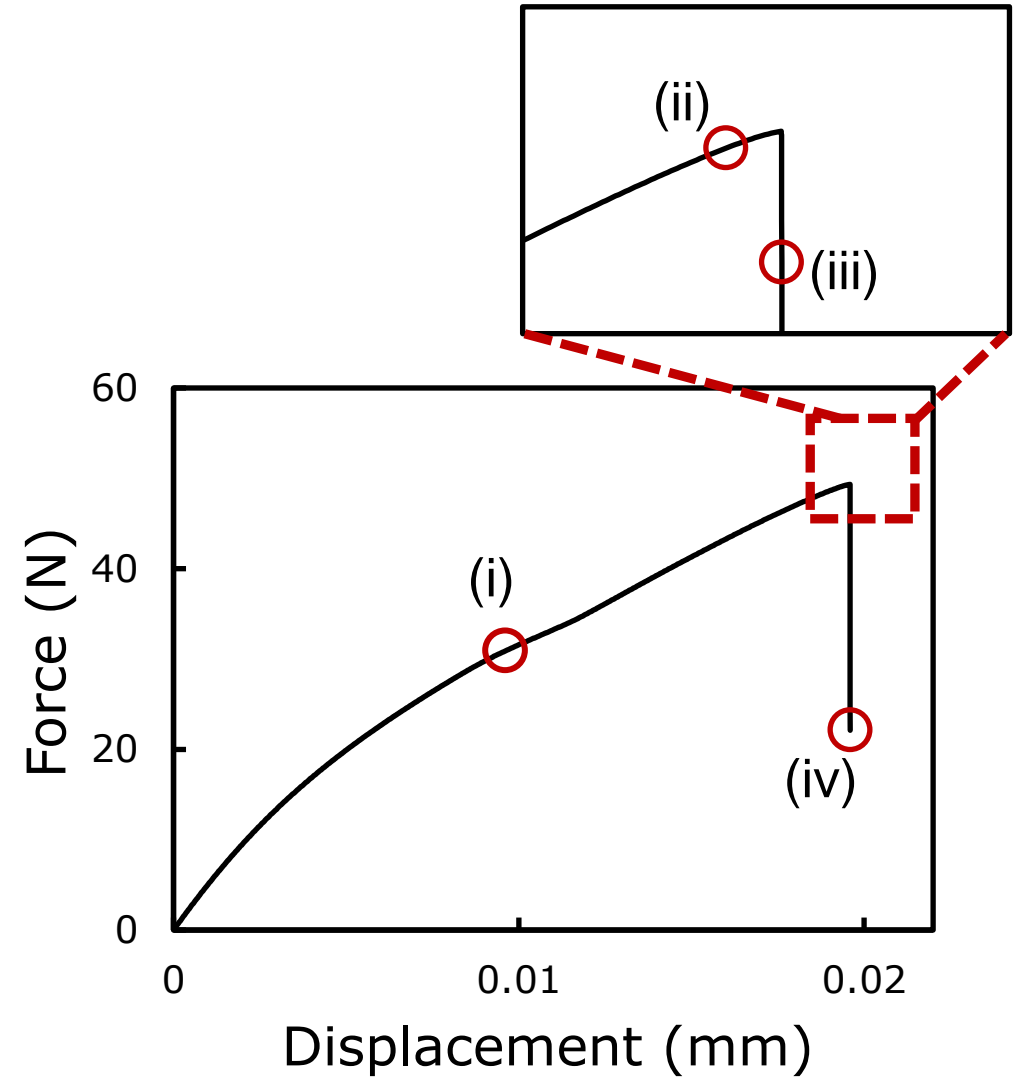
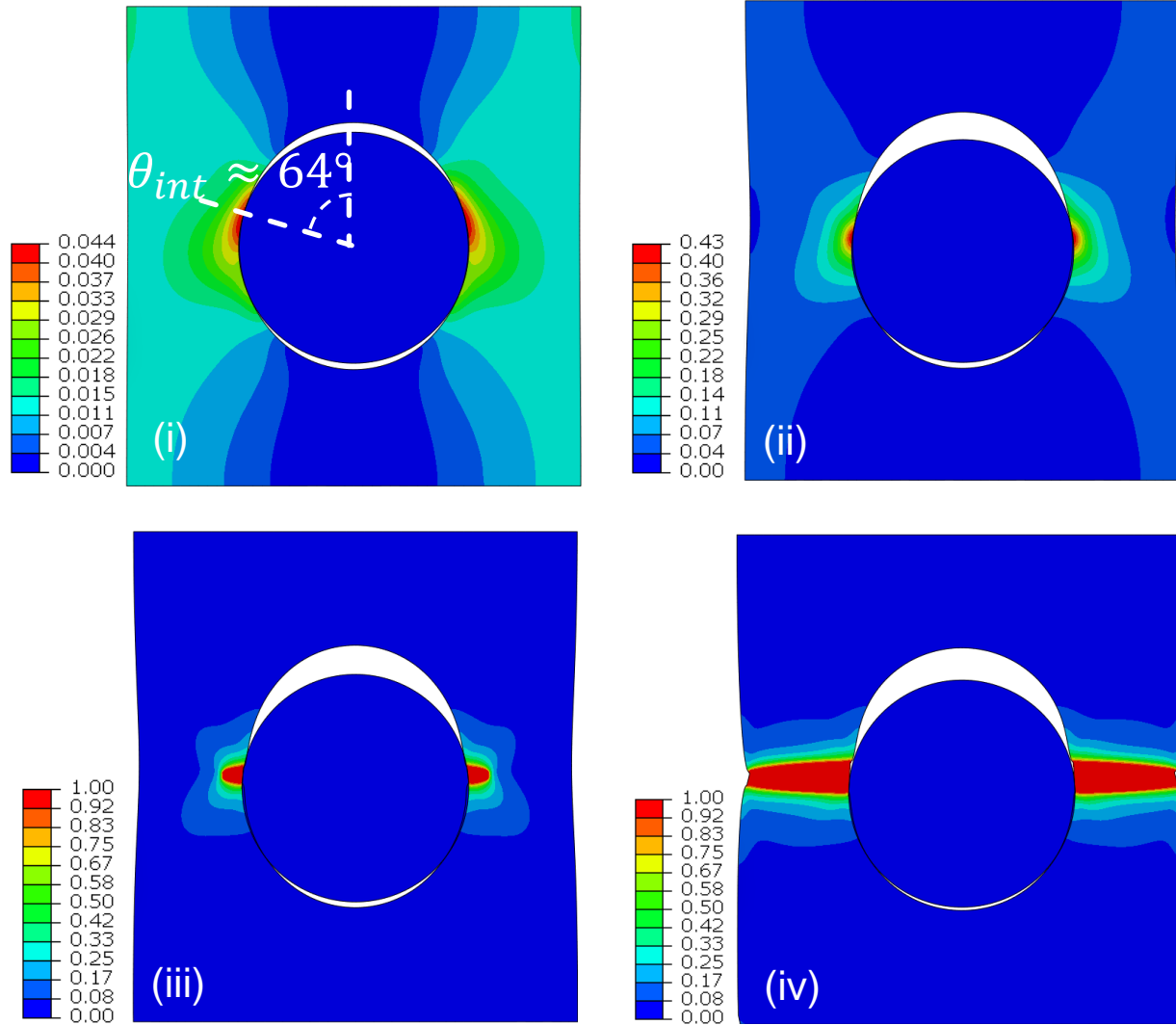
## Stress $S_{22}$ (MPa)

## Phase-field



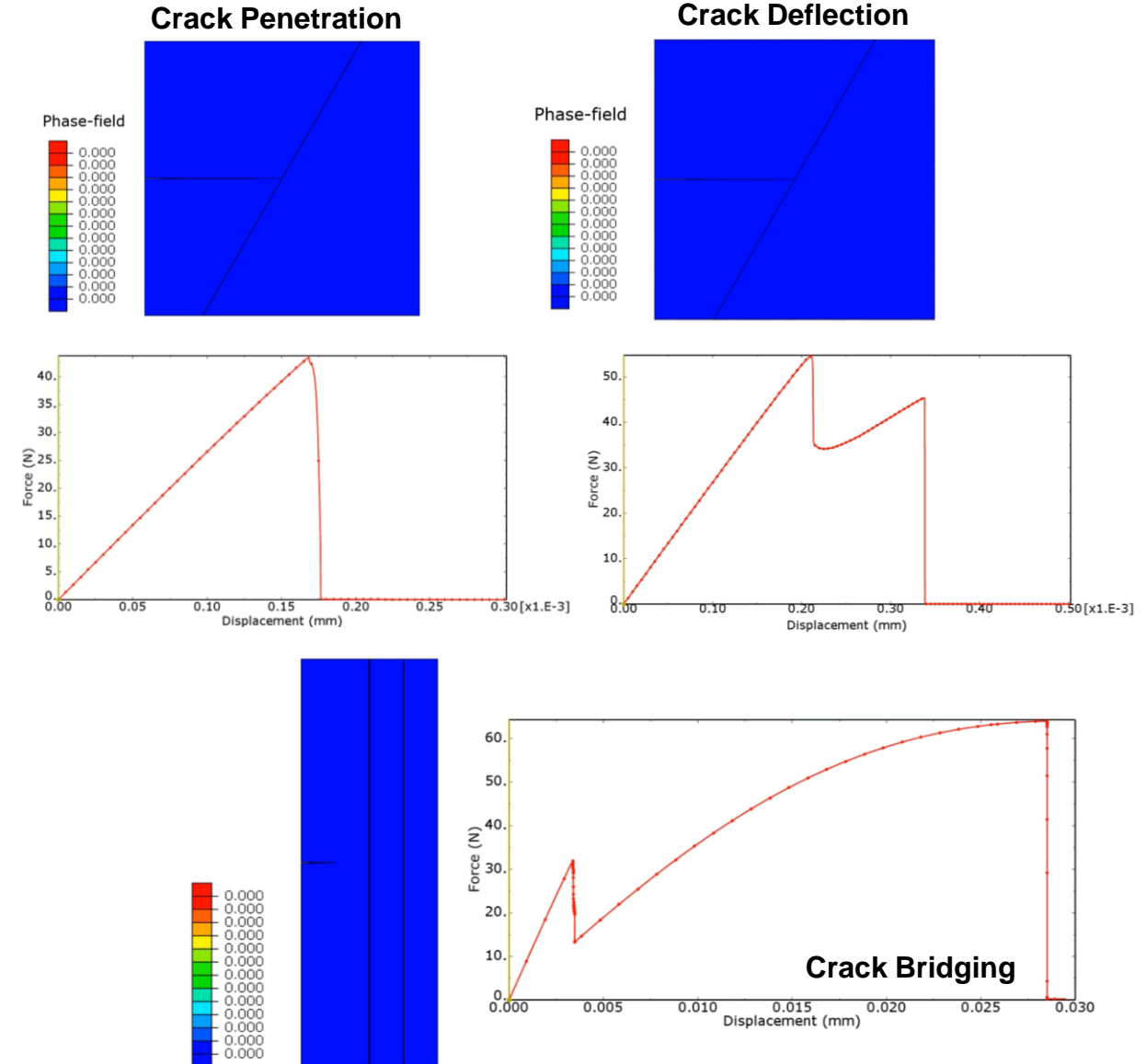
# Framework predictions

## Phase-field



# Conclusions

- A unified framework coupling large deformation phase-field and PPR CZM was developed to explore crack growth in hard-hard and hard-soft multi-material systems
- The framework can capture **crack deflection** and **crack penetration** in hard-hard composites containing weak interfaces in accordance with predictions of Linear Elastic Fracture Mechanics (LEFM)
- The framework captures an emergent crack growth mechanism in hard-soft (Cement-PVS) composites: crack bridging by the soft layer



# Thank you for your attention! Questions?

